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THESIS

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Roy D. McMaster Capt. USAF

DEPARTMENT OF THE AIR FORCE AIR UNIVERSITY (ATC)

AIR FORCE INSTITUTE OF TECHNOLOGY

Wright-Patterson Air Force Base, Ohio

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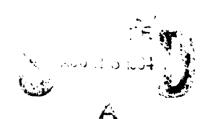
# COST EFFECTIVENESS OF "NOLA" CONTROLLED MOTORS, INCLUDING ! FFECT OF HIGHER HARMONICS

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COST EFFECTIVENESS OF

"NOLA" CONTROLLED MOTORS,

INCLUDING EFFECT OF HIGHER HARMONICS

#### THESIS

Presented to the Faculty of the School of Engineering
of the Air Force Institute of Technology
Air University
In Partial Fulfillment of the
Requirements for the Degree of
Master of Science

by

Roy D. McMaster

Capt. USAF

Graduate Electrical Engineer

December 1980

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#### **Preface**

The Air Force has a need to conserve energy and to correct the power factor on electric motors. This need brought about a thesis topic. It was proposed that a graduate student do an economic analysis of the "NOLA" Power Factor Motor Controller and the effects the controller may have on the power circuits. A computerized motor and controller simulation would be used to produce the economic analysis and effects on the power circuit.

I chose this thesis topic because I have an undergraduate background in power systems and a desire to better understand these systems. In this thesis I develop a digital-analog simulation model for the motor and controller and implement them on the computer. The data from the simulation is used to make the economic analysis and to determine the effects on the power system.

I would like to thank Dr. Frederick Brockhurst for his guidance throughout all stages of the thesis effort. I would also like to thank my wife for transcribing the rough draft and for her tolerance of me during the preparation of this thesis.

Roy D. McMaster

#### **Abstract**

An economic analysis of the NOLA Power Factor Motor Controller is accomplished and the effects of the harmonics produced by the controller are studied. The controller is placed in series with each leg of various sizes of wye-connected three-phase motors. The energy saved by the controller, the power factor correction, and the reflected harmonics under varying load conditions are studied to determine the economic advantages. Also the data from the controlled motor is compared to an energy efficient motor.

An analog-digital computer program is developed which models an induction motor and the NOLA controller. The computer model is used to determine and analyze the reflected wave shape produced by the controller.

The results of the study indicates that the energy efficient motor is the most cost effective alternative at the present time because of the high initial cost of the "NOLA" controller. Continued studies are recommended to determine the effects of the higher harmonics.

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#### I. Introduction

#### Background

In the last few years the public and industrial interest has turned to conserving energy due to the increase in cost of a barrel of oil from about four dollars in the early 1970's to over thirty dollars in 1980. This increase in energy cost led to the invention and development of a power factor motor controller by Frank Nola, an aerospace engineer working at the National Aeronautics and Space Administration's Marshall Space Flight Center in Huntsville, Alabama.

"By interrupting the voltage applied to the motor during portions (Alpha electrical degrees) of each half cycle, the NOLA controller attempts to achieve an essentially constant power factor operation. This results in lower core and winding losses, improving the efficiency of the Machine." The power factor controller (PFC) has been tested on over 50 motors at the Marshall Space Flight Center and has shown energy savings ranging from 0 to 10 percent at rated load and up to 75 percent at no load (Ref. 1: 197). percentage savings versus load for two 3-phase motors and a single phase motor are shown in figure 1 (Ref. 1: 197). Other hardware test results are illustrated in Reference 1; therefore, the purpose of this thesis was not to test the validity of the controller, but, rather, to conduct an economic analysis of the cost of using the controller with conventional induction motors versus the cost of using high

efficiency induction motors.

To conduct the economic analysis, it was necessary to have some way of obtaining real and reactive power consumption by the motor for a variety of load conditions, both with and without the NOLA controller. Therefore a computer model of the PFC and motor was developed and used to generate the data required to determine the economic advantages of using the PFC and it's effects on the power system.

A secondary objective was to investigate the nature of the harmonics impressed on the power system by the PFC.

#### Approach

The induction motor was modelled by an equivalent circuit and the mesh equations for the circuit were derived. The equations were put into a form suitable for solution on an analog computer and the analog computer was then simulated on a digital computer. This technique is here-after referred to as the analog-digital simulation. The motor was then coupled to the model for the PFC. Power requirements were obtained for a variety of operating conditions both with and without the controller for both conventional and energy efficient motors. These results were then used to conduct an economic analysis of each of the different possibilities.

#### Assumptions

The primary assumption underlying this approach is that

the computer simulation of PFC and induction motor provides reasonably accurate estimates of the real and reactive power requirements of the machine. Clearly the cost comparisons are only as valid as the data used to generate them.

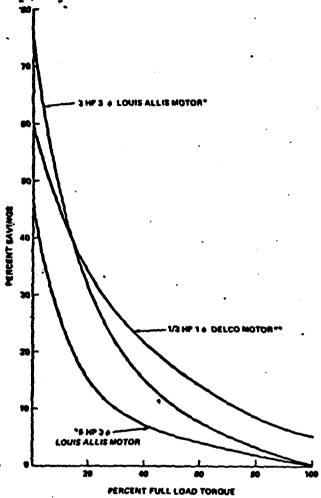
Fortunately, machine modeling techniques are well established and have been validated over the years. In addition, results obtained from the model compared closely to manufacturers' test results. The parameters used in the models were obtained from manufacturers' data. Additional assumptions regarding costs (motors, electricity, and controller) as well as period of operation were required to conduct the economic analysis. These are described in detail in Chapter V.

#### Sequence of Presentation

Chapter II describes the theory of operation of the PFC and how it was modelled in the computer program. Chapter III describes the equivalent circuit of the induction machine and presents a derivation of the equations required for the analog computer simulation of the machine. Chapter IV describes the over-all analog-digital simulation of the PFC and induction motor. Chapter V gives the assumptions and methods used to conduct the economic analysis. The final chapter contains conclusions and recommendations.

There are seven appendices. Appendix A contains the digital program to determine equivalent circuit parameter values and Alpha values for controlled states. Appendix B contains the tables listing the input/output data for motor

elements and Alpha values. Appendix C is the FORTRAN
listing of the analog-digital simulation of the PFC and
motor. Appendix D contains figures showing the reflected
waves of the controlled motors. Appendix E presents a
sampling of harmonic data from a Fast Fourier Transform.
Appendix F contains the calculations and tables used in the
economic analysis. Finally, Appendix G contains tables
showing comparisons of actual motor data and the simulated
data.



\* Data obtained from Auburn University Report

\*\* NASAMARSHALL SPACE FLIGHT CENTER (MSFC) DATA

PFC percent savings versus torque for various motors.

Figure 1

# II <u>Computer Simulation of the</u> "NOLA" Power Factor Controller

The "NOLA" Power Factor Controller, here after referred to as the PFC, is placed in series with each phase of a wye-connected three phase induction motor. The PFC corrects the power factor and reduces the power losses within the motor when the motor is operated at less than full load. Although the PFC is an electronic control system, it is modelled as an opened or closed switch (TRIAC) in Subroutine V3CONT.

This chapter begins with a brief discussion of the PFC's theory of operation as presented by the inventor.

This is followed by how the PFC is modelled for computer simulation.

#### PFC Theory of Operation

The PFC is an electronic circuit that monitors and controls the terminal voltage and the phase angle, or power factor, of the current applied to the motor.

The PFC senses the line voltage and current and produces a voltage proportional to the phase angle between the two. This voltage is summed with a reference voltage that is indicative of a desired phase angle. The difference in these two voltages is an error voltage which, after conditioning, controls the turn-on or firing angle of a solid

state switch (TRIAC) that is in series with the motor (see Figure 2). The TRIAC is turned on for a portion of each half cycle as in a typical phase control circuit such as used in a light dimmer switch. This varies the applied voltage to the motor as a function of the load and forces the phase angle between voltage and current to remain constant, within the limits of the motor, at the commanded value regardless of changes in load. Thus, by controlling the magnitude of the motor terminal voltage to only that necessary to over come torques attendent to less than fully loaded conditions, the losses associated with full line voltage are minimized (Ref 1:194).

#### Computer Simulation of PFC

As mentioned in the opening paragraph of this chapter, the PFC is modelled as an opened or closed switch which is switched open when the current approaches zero. The switch will stay open for a preset period of time which is called Alpha. Typical results of the switching action on the current and voltage are shown in Figure 3.

The logic of the 3-phase voltage controller, subroutine V3CONT, determines the correct position of the switch of each phase independently and is the same for each phase.

Therefore, only one phase of the three-phase controller will be explained. A "Mini" flow chart for subroutine V3CONT is shown in Figure 4.

The logic for phase one is as follows: Check the position of the switch. If the switch is closed then see if the preset point counter value has been exceeded. If the point counter value has not been exceeded, then the controller will skip all other tests on phase one and will not change the position of the switch. The point counter test allows the current time to leave zero value once the switch is closed. If the preset counter value is exceeded then the magnitude of the current is sampled. If the current is less than one tenth of an ampere then the current is approaching a zero crossing and the switch will be opened for the preset time of Alpha. When the switch is opened the voltage and current are set to equal zero and the point counter is reset. The switch is closed then the above tests are repeated until another current zero crossing is sensed.

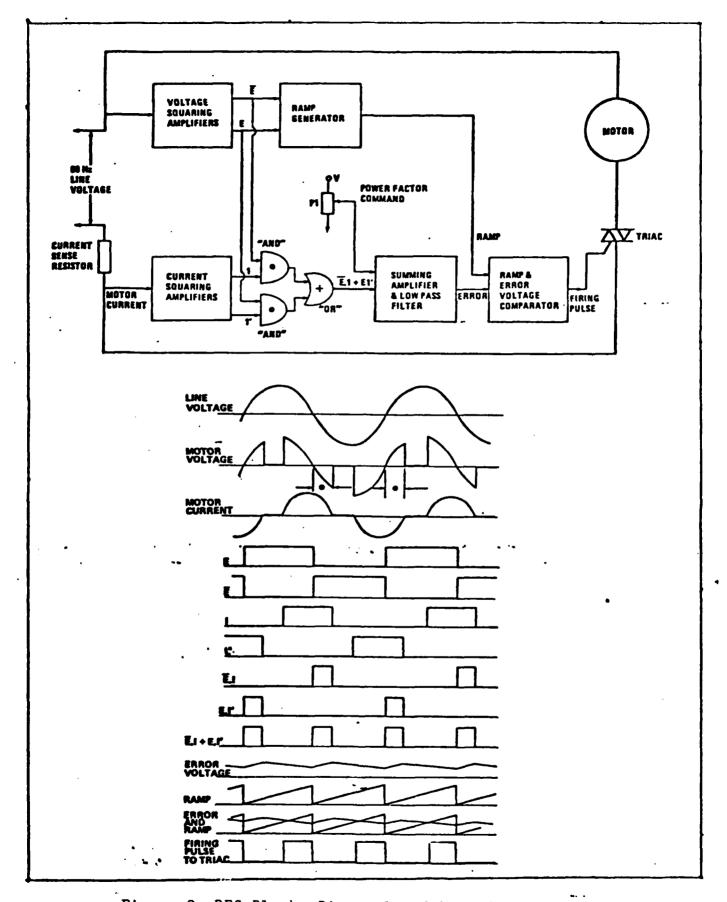
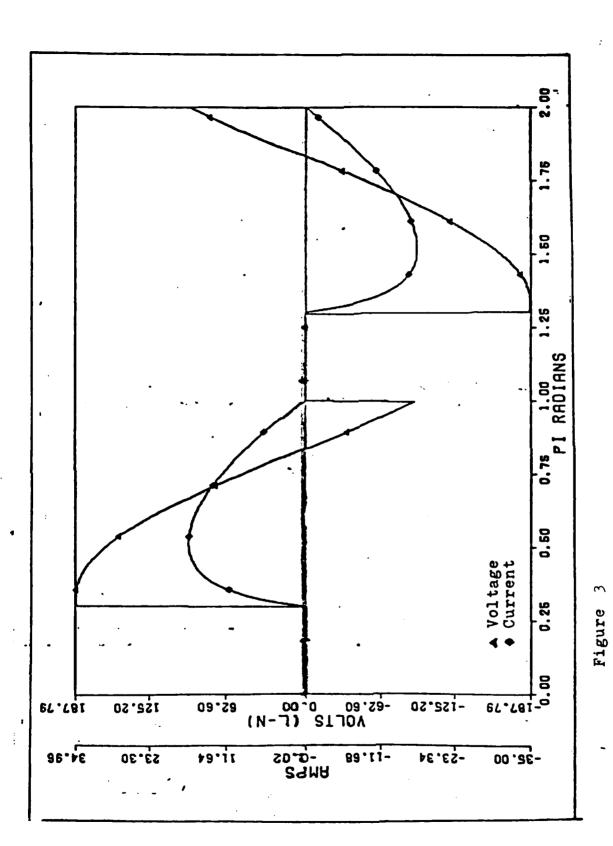


Figure 2 PFC Block, Diagonal and Wave Forms



5 Horse Power Energy Efficient with ALPHA equal 0.95 Reflected Voltage and Current Wave for

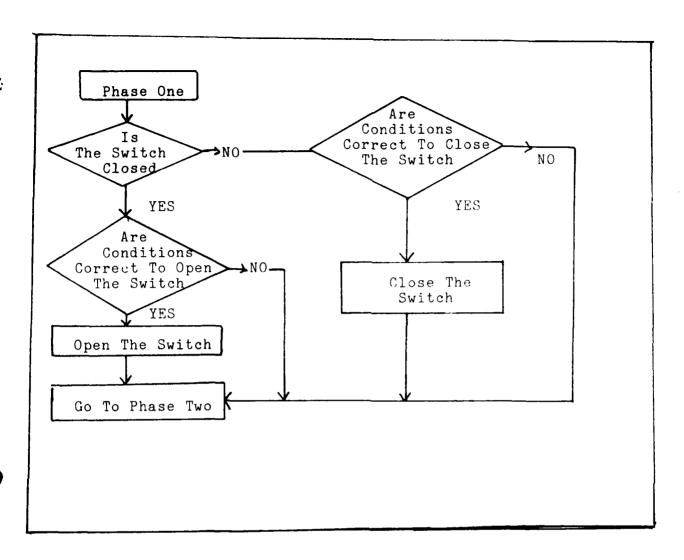


Figure 4 "Mini" Flow Chart For Subroutine V3CONT

#### III Mesh Analysis of a Wye-Connected Induction Motor

A mesh analysis of the per-phase equivalent circuit of a wye-connected induction motor is used to determine the currents within each portion of the motor.

#### Per-Phase Equivalent Circuit

The per-phase equivalent circuit is shown in Figure 5 (Ref.: 3) and represents the three major components of the motor which are typical of both energy efficient and standard motors. First, the stator is represented by elements Rl and Ll, where Rl is the stator resistance and Ll is the stator inductance. The input current Il is the total circulating current in the stator. Next, L2 and R2 represent the magnetizing inductance and core loss resistance in the core. The current I2 circulates in the core. The elements L3 and R3 represent the inductance and resistance in the rotor.

$$P_{c} = I3^{2}(R3(1-S)/S)$$
 (1)

If the values of elements of the equivalent circuit and the voltage applied are known, then the power output and losses of the motor may be calculated using mesh equations.

#### Derivation of the Mesh Equations

The mesh equations are derived by writing loop equations around each loop of the equivalent circuit (Figure 5).

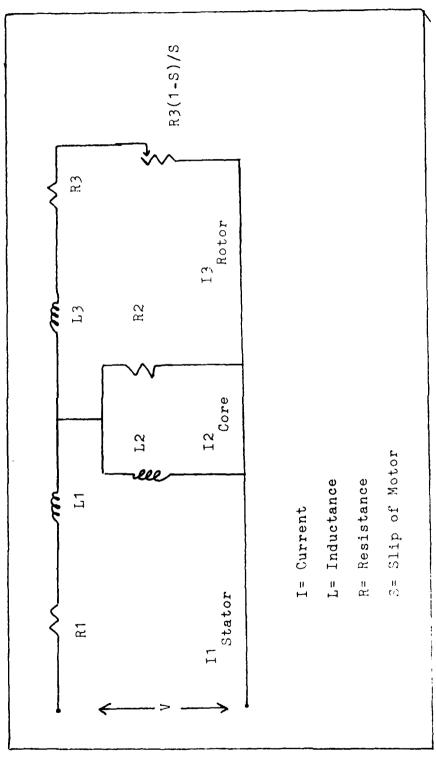


Figure 5 Per-Phase Equivalent Circuit

Then, combine the loop equations to solve for the current derivatives.

Figure 6 contains the current symbols used in the loop equations and the computer simulation.

Y1 = I1, Y2 = I2, Y3 = I3

X1 = 
$$\frac{DI1}{dt}$$
, X2 =  $\frac{dI2}{dt}$ , X3 =  $\frac{dI3}{dt}$ 

V = Input Voltage

Figure 6. Loop Equation Symbols

The Loop equations are as follows:

$$V = R1Y1 + L1X1 + L2X1 - L2X2$$
 (2)

$$O = -L2X1 + L2X2 + R2y2 - R2X3$$
 (3)

$$O = -R2Y2 + L3X3 + R3Y3 + R2Y3 + R4Y3$$
 (4)

The equations are combined to solve for the derivatives X1, X2, and X3.

$$X1 = (-R1Y1 + R2Y2 - R2Y3 + V) / 11$$
 (5)

$$X2 = (L2R1Y1 / (L1 + L2) - L2V/(L1 + L2) + R2(Y2 - Y3)) / ((L22/(L1+L2)) - L2)$$
(6)

$$X3 = (R2Y2 - (R3 + R2 + R4) Y3) / L3$$
 (7)

#### Analog Configuration

An analog integration of equations (5), (6), and (7) is

used to obtain point by point data for the steady state solution.

Figures 7 and 8 represent the analog configuration of the per-phase equivalent circuit as used in the analog-digital simulation. The program for this is contained in Appendix C.

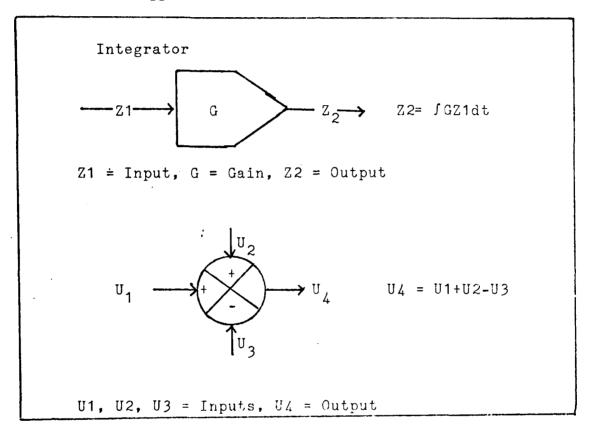


Figure 7 Analog Integrating and Summing Elements

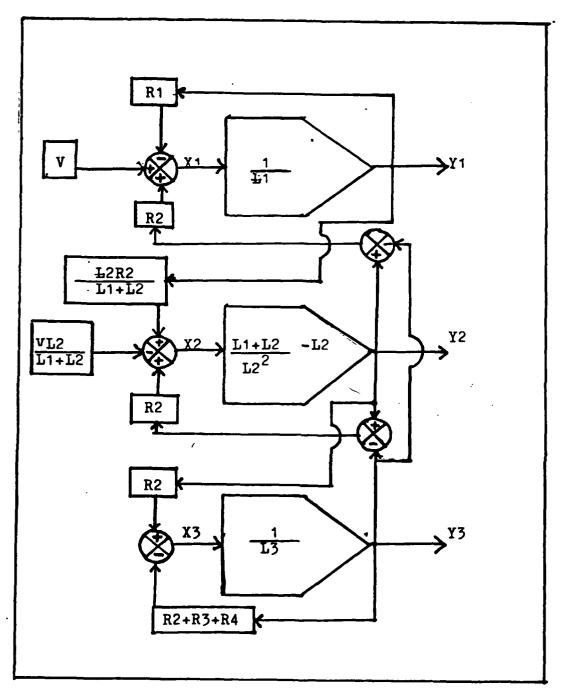


Figure 8 Per-Phase Analog Configuration for A Wye-Connected Induction Motor

# IV. Analog-Digital Simulation of the Induction Motor and Controller

This chapter gives a brief description of the procedures and computer programs used to produce the data generated for the cost analysis and for the harmonic reflected wave shapes. Figure 9 is a mini flow chart showing the steps taken to generate the required data.

#### Computation of Equivalent Circuit Values

The equivalent circuit values were computed using the program listed in Appendix A. Manufacturer's no load and full load test data (Appendix G) were used to generate the values for the parameters of the motor equivalent circuit shown in Chapter III.

The program and data were furnished by Dr. Frederick Brockhurst (Ref. 2).

#### Alpha Angles

The same program and reference data which were used to compute the equivalent circuit values were also used to compute the power factor and Alpha angle to be used in the motor controller simulation.

The Alpha angle was computed in subroutine CONT which uses an estimating parameter technique. The input/output data is shown in Appendix B.

#### Analog-Digital Integration

A program was written to simulate the combined operation

of the PFC and induction motor. The program (listed in Appendix C) is capable of calculating the motor losses for a variety of load conditions. This program was used to generate the data required to plot the reflected voltage and current wave shapes listed in Appendix D. The data may also be used to determine harmonic content of the reflective wave

The performance of the machine simulation was verified by comparing calculated values of current, power, speed, efficiency, and power factor to manufacturers' data. These results are shown in Appendix G and agreed quite closely.

#### Computation of Harmonic Content of the Reflected Current

The harmonic content of the reflected current was calculated by using a Fast Fourier Transform program as listed in Appendix C.

A sampling of the results of the Fourier Transform data is shown in Appendix E.

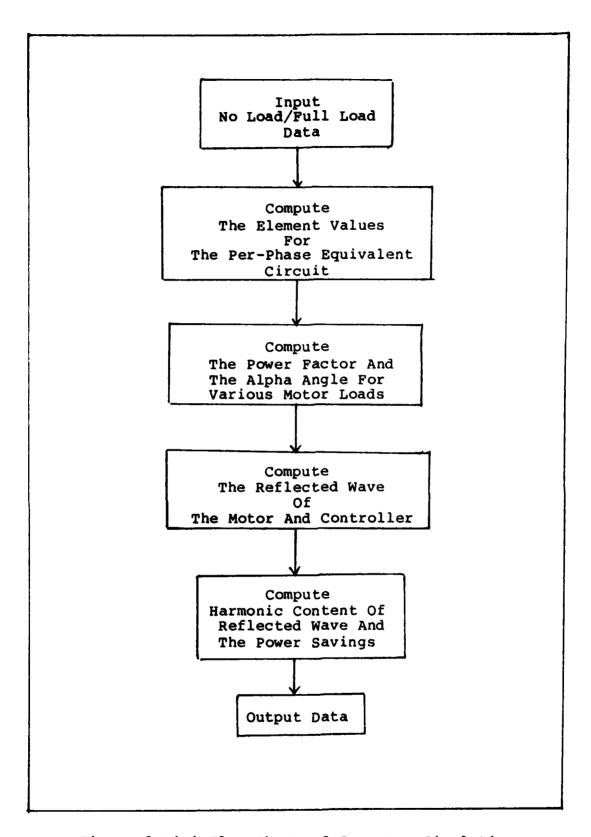


Figure 9 Mini Flow Chart of Computer Simulation

#### V. Cost Analysis of Controller and Motor

This chapter introduces 6 possible cases for motor/controller configurations. The assumptions that apply to the analysis and the method by which the analysis was prepared.

The cost analysis is separated into 6 possible cases for the 5 horsepower and the 10 horsepower motors. Each case uses a simple payback method based on a fixed number of running hours per year, the calculated power savings and the estimated cost of the motor and controller.

Equation 8 shows the method used to calculate the estimated cost savings per year.

\$saved/year = hours/year X estimated watts saved X
\$cost/kilowatt hour X kilowatt/1000 watts (8)

The following assumptions were used in the above equation.

- 1. 8760 hours per year was used to show continuous operation. If a motor does not operate continuously or operates at various loading then the motor data shown in tables A and B may be prorated to estimate the annual savings.
- 2. \$0.06 per kilowatt hour was used as an average cost for power. This cost can be adjusted to fit the estimated

energy cost in a particular area of the country.

- 3. A standard 5 horse power motor costs \$329.00.
- 4. An energy efficient 5 horse power motor costs \$370.00.
- 5. A controller for a 5 horse power motor costs \$550.00.
- 6. A standard 10 horse power motor costs \$505.00.
- 7. An energy efficient 10 horse power motor costs \$655.00.
- 8. A controller for a 10 horse power motor costs \$850.00.
  Assumptions 3 through 8 were based on local vendor prices
  (1980).

The simple payback method is used to show the estimated payback in years. Once the exact cost of a system and power is known for a given location and time then a life cycle cost analysis may be used. The formula for the simple payback method used is

yrs to payback = system cost/ cost savings/ year (9)

The following 6 cases were considered:

Charle Street Street Constitution of the Const

- 1. The first case is the comparison of an energy efficient motor without motor controller with a standard motor without motor controller.
- 2. The second case is the comparison of an energy efficient motor without controller with a standard motor with motor

controller.

- 3. The third case compares an energy efficient motor with motor controller with a standard motor with motor controller.
- 4. The fourth case compares an energy efficient motor with motor controller with a standard motor without a motor controller.
- 5. The fifth case compares a standard controlled motor with a standard uncontrolled motor.
- 6. The sixth case compares an energy efficient controlled motor with an energy efficient uncontrolled motor.

Each case except #2 and #3 also compare the simple payback in years for a new installation and retrofit for each motor loading.

All of the data and calculations for the six cases using 5 and 10 Hp motors are shown in Appendix F. A portion of the data is shown below to illustrate the method and results.

Table A shows the energy savings (or less) for each of the six cases using 5 Hp motors. For example case 1 shows the savings obtained by using an energy efficient motor (EEM) instead of a standard motor. Similarly case 2 shows the savings obtained by using an EEM instead of a controlled standard motor. Note that for cases 2 the EEM is more efficient down to about half-load, but below half-load the

controlled standard motor is more efficient. This is indicated by the negative signs for the last three entries in column #2. Note that from column 6, there appears to be little benefit from putting a controller on an EEM unless it is very lightly loaded.

Once the differences in wattage for the different cases and loads were known, equation 8 was used to calculate the annual dollar savingS (loss). Table B shows these results for the 5 Hp motor. Again negative signs indicate that the second alternative is more economical.

Finally the payback period was calculated both for new installation and for retrofit installations. Table C shows the payback periods for Case I using 5 Hp motors. For new installations only the difference in cost must be repaid, while for a retrofit installation the entire cost of the motor, controller (if used), and labor must be repaid.

Tables D and E show payback periods for the 5 Hp and 10 Hp motors, respectively, for all six cases. Negative numbers in these tables indicate that the option being considered has a higher operating cost. The details of the exact cost used to calculate the payback periods are shown in Appendix F.

5 HP

∆ Wattage for (Situation)

- . Energy Efficient (uncont) VS Standard (uncont)
- . Energy Efficient (uncont) VS Standard (Cont)
- Energy Efficient (cont) VS Standard (cont)
- Energy Efficient (Cont) VS Standard (uncont)
- . Standard (cont) VS Standard (uncont)
- 6. Energy Efficient (cont) VS Energy Efficient (uncont)

## Savings in Watts

9#	m	-41	-45	-7	-30	09	45	97	150
<b>4</b>	0	-54	21	10	43	86	158	192	243
#	67	26	84	57	90	178	191	209	263
<b>€</b>	67	110	63	47	46	80	က	18	20
#5	64	151	108	54	77	20	-41	-79	-130
#1	64	97	129	64	120	118	116	113	113
HP Load	2	4.5	4.0	3.75	3.0	2.5	2.0	1.25	0.75

Table A

5 HP Savings/Year Based on \$0.06 KWH

HP Load	HP Load (Situation)		Comparison	son		
	#1	**	e #≠	*	S #	9
2	\$33.63	\$ 33.63	\$35.22	\$ 35.22	0 \$	\$ 1.58
4.5	\$50.98	\$ 79.36	\$57.82	\$ 29.43	\$-28.38	\$-21.55
4.0	\$67.80	\$ 56.76	\$33.11	\$ 44.15	\$ 11.04	\$-23.65
3.75	\$33.63	\$ 28.38	\$24.70	\$ 29.96	\$ 5.26	\$ -3.68
3.0	\$63.07	\$ 40.47	\$24.18	\$ 47.30	\$ 22.60	\$-15.77
2.5	\$62.02	\$ 10.51	\$42.05	\$ 93.55	\$ 51.50	\$ 31.54
2.0	\$60.97	\$-21.54	\$ 1.58	\$ 84.62	\$ 83.05	\$ 23.65
1.25	\$59.39	\$-41.52	\$ 9.46	\$109.85	\$100.92	\$ 50.98
0.75	\$59,39	\$-68,33	\$10.51	\$138.23	\$127.72	S 78.84

Table B

### 5 HP

### Simple Payback

### Cost/Savings per Year

Standard \$329.00, Energy Efficient 370.00
A= Cost = \$41.00, B= Cost = \$370.00 + 20% = \$444.00
Installation Cost

HP Load	Α	В
5	1.22 yrs	13.20 yr
4.5	0.80 yrs	8.71 yr
4.0	0.60 yrs	6.55 yr
3.75	1.22 yrs	13.20 yr
3.0	0.65 yrs	7.04 yr
2.5	0.66 yrs	7.16 yr
2.0	0.67 yrs	7.28 yr
1.25	0.69 yrs	7.48 yr
0.75	0.69 yrs	7.48 yr

B= Retrofit - Replacing Standard Motor with Energy Efficient
+ 20% Motor Cost Installation

A= New Installation, Cost of Energy Efficient vs Standard Motor based on continuous operation

Table C

5 Horse Power Motor and Controller Comparisons

A=New Installation, B=Retrofit

Simple Payback in Years

Load				Situ	Situation					
Horse										
Power	18	18	2A	3A	<b>4</b> A	<b>4</b> B	5A	5B	<b>6A</b>	<b>6</b> B
5.0	1.22	13.22	0	1.16	16.78	28.22	04	savings-		
4.5	0.88	8.71	0	0.71	20.08	33.78	-19.37	-19.37	-25.2	-25.5
4.0	09.0	6.55	0	1.24	13.39	22.51	49.81	49.81	-23.3	-23.3
3.75	1.22	13.20	0	1.66	19.73	33.18	104.56	104.56	-149.5	-149.5
3.0	0.65	7.04	0	1.70	12.49	21.0	24.33	24.33	-34.9	-34.9
2.5	99.0	7.16	0	0.98	6.32	10.23	10.68	10.68	17.4	17.4
2.0	0.67	7.28	+23.63	25.95	86.9	11.75	6.62	6.62	23.3	23.3
1.25	69.0	7.48	+12.26	4.33	5.38	9.05	5.45	5.45	10.8	10.8
0.75	69.0	7.48	+7.48	3.90	4.28	7.20	4.30	4.30	7.0	7.0

Table D

10 Horse Power Motor and Controller Comparisons

A= New Installation, B= Retrofit

Simple Payback in Years

		v 0 8 7
	<b>6</b> B	-9.45 67.40 21.28 11.47
	6A	-9.45 67.40 21.28 11.47
	5B	NONE -14.84 50.56 8.84
	5A	NONE -14.85 50.56 8.84
	4B	33.72 18.77 18.31 15.37
Situation	44	20.66 11.50 11.24 9.42
Si	3A	3.27 1.10 2.19 14.49
	2A	NONE NONE NONE -10.94
	18	5.75 10.60 15.98 24.10
	14	1.15 2.14 3.20 4.83
Horse	10404	10 7.5 5.0 2.5

Table E

### VI. Conclusions and Recommendations

### Conclusions

The analog-digital computer simulation of the PFC and motors is effective for generating the data required for the economic analysis of the "NOLA" controlled motors. The "NOLA Controller" showed an energy savings and effectively controls the power factor of motors operating at less than full load. Although it does conserve energy, the PFC does not provide a cost effective way to conserve energy at this time due to it's high initial cost.

The energy efficient motor proved to be cost effective when used in new installation or scheduled replacement.

Retrofitting with energy efficient motors for the purpose of energy conservation is not cost effective.

No conclusions were reached about the effects of the higher harmonics produced by PFC.

The wave shapes of the reflective waves were produced in this thesis and lead one to believe that harmonic problems may be created by the PFC. Additional thoughts on this subject are covered in the recommendation section of this chapter.

### Recommendations

Based on the data presented in this thesis and the cost of the PFC, future consideration should be given to the use of the PFC if the initial cost decreases. At the present time energy efficient motors should be used in lieu of

standard induction motors.

The effects of the higher harmonics should be explored.

The areas of explanation should be as listed below.

- 1. The effects of a harmonic dampening device (linear filter) used on the line side of the PFC using different motor load configuration.
- 2. The effects the harmonics may have on sensistive electronic equipment.
- 3. The effects of the harmonics on a typical secondary power distribution system versus motor size.

### Bibliography

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   Georoge C. Marshall Space Flight Center Marshall Space flight center, Alabama 35812, Conference Record IEEE Industrial Applications Society IAS Annual Meeting 1980, p. 194-198.
- 2. Brockhurst, F. Private Communications June 1979.

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 Hudson, Ralph G. <u>The Engineers Manual</u>. John Wiley And Sons Inc. N.Y. 1944. Figure 1004, pg. 240.

## Appendix A

Digital Program to Determine

Motor Element Values And

The ALPHA Values For Controlled

State.

### List of Input Variables

Ml = Input Flag

V = Line to Line Voltage

IF = Full Load Current

Pin = No Load Input Power

PIF = Full Load Input Power

PFN = No load Power Factor

Pff = Full Load Power Factor

HP = Full Load Horse Power

RPM = Synchronous Speed

RPMF = Full Load Speed

	PROGRAM NINE 74/74 OPT=1 PHO4P	11/15/80 07-11-53	PAGE 1
7	PROGRAM WINE (INPLI, CUIPUT, TAPES=INFUI, TAPE6=OUTPUI)		
	COMPLEX 71,72,72H1,11,12,1PHT,V1,E,QC,XH,VA,1FC,INC,V1C		
5	REALLIL, RIJE, IL, IFK, IFX, INR, IKX .IA COMMON RI, XM, RC		
	[		
	GC TO 230		•
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	1/50R = 0.0		
15	. " " R11= ",R11;" R22=		
	. X11= ", X11," X22= ", X2 . RUC =", RCC," XMM = ", XM		
	111		
36	R1=R11 R2 =022		
	"		
35	VI=CFPE(X(VII+G-D)		
	!		
	FG=CPPLX(RCC, C.0) 2Ph1=(PC*X*)/(4C*X*)		
30	07 01 09		
	V = L-L VOLTA IF = FULL LCAD		
35	0 2		
	PFN = FULL LCAD		
	MP = FULL LCAD MORSEP		
0,5	PPF = SYNCHOCHOUS SPEED		
	260 FEED (5,210) V. 1F, IN		
1.5	0F7.4) 0(2x,F9.4))		
	V=V/SGRT(3.) PIN=PIN/3.		
	FIFIFIFY %.		
51	VAF # PIF/PFF PO # HP# 745./3.		
	S# (PPF-RPM)/RPM		
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2.85	69	# 15 EE	E CARS(IZ)**Z*RZ LF-po(I)/(CARS(IFC)**2)					ı
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244 X247,01 17 372-49-10-10-10-10-10-10-10-10-10-10-10-10-10-	12	0*G=TX	055×19					1
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10   10   10   10   10   10   10   10		112 V1C	HPLX(0.,X1) FFC*R1+12*R2/S4X12*(12+IFG)					ł
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X		IF (4PS	2					1
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20		SeSIN( ALPHA))			
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130 PCOPE=CABS(I1)**2*R2C PCU=CABS(I1)**2*R1+CAPS(I2)**2*R2 FINE CHIAPTORE**PCU EFF=PWECH1/PTORE**PCU EFF=PWECH1/P46*5 FF=COS(IT) FF=COS(IT)**II FF=COS(IT)*		1			
FIN = PMECHI/PCORE.PCU  EFF=PMECHI/PIN  RPH1=(1,-S)*cPP  III = CAS(II)  HP=PYE(HI/746.5)  FF=CCS(IHI/746.5)  FRINT*, "CONTCUTPUT"  PRINT*, ""  PRINT*, ""  PRINT*, ""  FETUPN  END  END	35	Ł			
RPM1=(1,-S)*cPF  I1L =CABS(I1)  HP=PFCH1746.5  FF=COS(THETA1)  FRINT**  MRITE(6,150) HP , RPM1 , EFF , PF , VA , PIN , I1L , ALPHA , V1  FRINT**  PRINT**  PRINT**  RETURN  END  END  END		FIN = PMECH1+PCORE+PCU EFF=PMECH1/PIN			
HP=PFE(H1/746.5) FF=CCS(TH=TA1) FRINT**." WRITE(6.150) HP , RPM1 ,EFF ,PF ,VA ,PIN ,111 ,ALPHA ,V1 150 FORMAT(1X,9F10.4) PRINT**." PRINT**." RETUPN END END		RPH1=(1S) *cPP I1L =CABS(I1)			
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150 FORMAT(11X,9F10.4) PRINT*, "		. APMI SEFF SPF SVA SPIN	, ALPHA		
PRINT.". RETURN END SYMBOLIC REFERENCE MAP (R=1)	45	FORMAT(1X,9F10.4)			
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Appendix B

Tables of Input/Output

Data for Motor Element and

Alpha Values

5 HP Energy Efficient (A)

PERSONAL PROPERTY PRO

CHARLE PARTICIPATION OF THE PROPERTY OF THE PR

V= 230.0 volts, I Full Load= 12.3 amps, I No Load= 4.54 amps,  $P_{\mathrm{IN}}$  No Load= 225.0 watts, Power In Full Load = 4288.0, Power Factor NO Load = 0.125, Power Factor Full Load = 0.874, HP= 5.0, RPM= 1800, RPM Full Load= 1751.0 Input

R1= 0.5037 ohms, R2= 0.3286 ohms, RCC= 254.273 ohms, X1 = 0.9623 ohms, X2 = X1, XMM = 28.457 ohms Equivalent CKT Values Calculated

	Vl volts	132.7	128.06	120.9	117.17	103.1	94.6	85.4	65.4	52.09
	တ	0.02875	0.0275	0.0275	0.0275	0.02875	0.0275	0.0275	0.03	0.0275
	ALPHA	0.0	0.3	0.55	0.65	0.95	1.10	1.25	1.55	1.75
11	Amps	12.225	11.39	10.75	10.42	9.4	8.41	7.59	6.23	4.63
	P <sub>IN</sub> watts	53	3828.27	69	66	74	46	0	10	ر د
	PF	87.85	87.48	87.48	87.48	87.85	87.48	87.48	88.17	88.48
	EFF	8801	881	81	81	301	ヸ	3,1	161	81
		•	ω.	Φ.	∞.	8.	8.	æ.	œ	æ.
	RPM	48.25	1750.5 .8	50.5	50.5	48.25	50.5	50.5	46.0	50.5
Output	RPM	48.25	1750.5	1750.5	1750.5	1748.25	1750.5	1750.5	1746.0	50.5

Table F

### 5 HP Energy Efficient (B)

V R1 R2 R3 L1 L2 230.0 0.5037 254.273 0.3286 0.9623 28.457

- M ALP S
- 0 0.0 0.02875
- 0 0.3 0.0275
- 0 0.65 0.0275
- 1 1.10 0.0275
- 0 0.95 0.02875
- 0 1.25 0.0275
- 0 1.55 0.03
- 1 1.75 0.0275

Table G

V= 460.0 volts, I Full Load= 7.06 amps, I No Load= 3.85 amps, P<sub>IN</sub> No Load= 335.0 watts, Power in Full Load= 4423.0 watts, Power Factor No Load= 0.11, Power Factor Full Load= 0.787 Horse Power= 5.0, RPM= 1800, RPM Full Load= 1747.0

R1= 1.6227 ohms, R2= 1.4443 ohms, RCC= 735.012 ohms, X1 = 2.9204 ohms, X2 = X1, XMM = 66.316 ohms Equivalent CKT Values Calculated

44

Vl	265.55 241.88 233.99 210.11 187.61 101.33	
'n	0.03125 0.03 0.03 0.03 0.03125 0.0325 0.0325	1
ALPHA	0.0 0.2 0.45 0.55 0.80 1.00 1.15	
I1 Amp	6.897 6.123 6.123 5.923 5.321 4.8741 4.2876 3.494	,
P <sub>in</sub> Watts	4342.65 3937.60 3476.13 3252.16 2624.83 2169.02 1704.00 1097.10	
स्	79.03 78.23 78.23 78.23 79.03 79.76	
Eff	8626 8624 8624 8624 8624 8624 8627	
		•
RPM	1743.75 .8 1746.00 .8 1746.00 .8 1746.00 .8 1746.00 .8 1741.50 .8	•
Output HP RPM		

84868988

Table H

## 5 HP Standard (B)

V R1 R2 R3 L1 L2 460 1.6227 735.012 14443 2.9204 66.316

M ALP S

0 0.0 0.03125

0 0.2 0.03

0 0.55 0.03

1 1.0 0.03125

0 0.8 0.03

0 1.15 0.03

0 1.45 0.0325

1 1.70 0.0325

Table I

10 HP Standard (A)

watts, P<sub>IN</sub> Full Load=8533.0 watts, PF No Load= .094, PF Full Load=.852, HP= 10.0, RPM= V=460 volts, I Full Load= 12.6 amps, I No Load= 5.1 amps,  $P_{in}$  No Load=379.0 1800, RPM Full Load= 1755 Input

R1= 1.0555 ohms, R2= .59318 ohms, RCC= 657.776 ohms, X1 = 1.985757 ohms, X2 = X1, XMM = 50.228416 ohms Equivalent CKT Values Calculated

46

	۷٦	265.6	257.4	243.3	235.9	227.5	208.1	191.3	166.6	147.0	120.4	83.1	59.59
	w	.02625	.025	.025	.025	.025	.025	.025	.02625	.025	.025	.02625	.02624
	ALPHA	0.00	0.25	0.50	0.60	0.70	0.9	1.05	1.25	1.40	1.60	1.90	2.15
11	Amps	12.41	11.59	10.96	10.63	10.25	9.37	8.62	7.78	6.62	5.42	3.88	2.79
	P <sub>IN</sub> Watts	8475.42	7626.19	6814.24	6407.43	5961.65	4984.12	4212.27	3335.73	2487.97	1668.50	828.77	426.71
	PF	85.70	85.19	85.19	85.19	85.19	85.19	85.19	85.70	85.19	85.19	85.70	85.70
	Eff	.887	.8883	.8883	.8883	.8883	.8883	.8883	.887	.8883	.8883	.887	.887
	RPM	1752.75	1755.0	1755.0	1755.0	1755.0	1755.0	1755.0	1752.75	1755.0	1755.0	1752.75	175.75
Output	HP	10.08	9.08	8.11	7.63	7.09	5.93	5.01	3.97	2.96	1.99	0.986	0.507
	HP	10.0	0.6	8.0	7.5	7.0	0.9	5.0	4.0	3.0	2.0	1.0	0.5

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### 10 HP Standard (B)

V	R1	R2	R3	Ll	L2
460	1.0555	657.776	0.5932	1.9875	50.2284

M	ALP	S
0	0.0	0.02625
0	0.5	0.025
0	0.7	0.025
1	1.05	0.025
0	1.40	0.025
0	1.60	0.025
0	1.90	0.02625
1	2.15	0.02625

Table K

# 10 HP Energy Efficient

watts, Power in full Load = 8354.0 watts, Power Factor No Load = 0.09, P.F. Full Load = .867, V= 230.0 volts, I Full Load= 24.2 Amps, I No Load=8.16 amps, P<sub>IN</sub> no load=291.0 HP= 10.0, RPM= 1800, RPM Full Load=1756.0 Input

R1= 0.23682 ohms, R2= 0.14646 ohms, RCC= 200.2742 ohms, X1 = 0.624716 ohms, X2 = X1, XMM = 15.6945 ohms Equivalent CKT values calculated

	Output					11	(	•	į
HP HP	НР	RPM	3 3 3	PF P	P <sub>IN</sub> Watts	Amps	ALPHA	အ	7
10.0	10.11	1752.75	.9001		8382.4	24.18	0.0	.02625	
9.0	9.14	1757.25	.9031	86.41	7548.7	22.14	0.1	.02375	131.5
8.0	8.08	1757.25	.9031		9.8299	20.82	0.45	.02375	
7.5	7.42	1757.25	.9031		6131.0	19.95	0.60	.02375	
7.0	6.92	1757.25	.9031		5716.8	19.26	0.70	.02375	
0.9	90.9	1757.25	.9031		5038.65	18.08	0.85	.02375	
5.0	4.93	1757.25	.9031		4072.88	16.26	1.05	.02375	
4.0	4.04	1757.25	.9031		3343.68	14.73	1.20	.02375	
3.0	3.00	1757,125	.9024		2481.28	12.81	1.40	.024375	
2.0	1.98	1757.25	.9031		1632.3	10.29	1.60	.02375	
1.0	1.01	1752.75	.9001		840.75	7.66	1.90	.02625	
0.5	0.5	1752.75	.9001		414.99	5.38	2.15	.02625	

Table L

### 10 HP Energy Efficient (B)

 V
 R1
 R2
 R3
 L1
 L2

 230.0
 0.23682
 200.2742
 0.14646
 0.624716
 15.6945

M ALP S
0 0.0 0.02375
0 0.45 0.02375
0 0.70 0.02375
1 1.05 0.02375

Table M

Appendix C

Analog-Digital Simulation

Computer Program

### List of Input Variables

V = Phase to Phase Voltage

Rl = Resistance in Ohms

R2 = Resistance in Ohms

Ll = Inductive Reactance

L2 = Inductive Reactance

M = FLAG, if Equal to 0 then New DAta will be Read

S = Slip of Motor

ALP = ALPHA Angle

```
ENABLE THE VOLTAGE CONTROLLER SET CONTRL POSITIVE ******
PROSEAM NINE(PLOT,INPUT,OUTPIT,FAPES#INPUT,IAPEG#OUTPUT)
BIMENSION Y(21),X(22),GA(21),PE(26),XX(4,20),H(3)
                                              OIMENSION ZZI(ZL),77Z(ZQ),773(Z),1FL(T) ,NN(S)
OIMENSION AC1(S4S), AC4(S4S), WI1(S1S)
DIMENSION REC(S43), RIM(S43), IWK(3420), MK(342°)
DIMENSION FREC(S43)
                                                                                                                                                                                                                                                                                                                                           FREQUENCY , T = TIME IN SECONDS. ----
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     HE OUTPUT FLAG FOR THE I HIRD CYCLE OF GURRENT
                                                                                                                                                                                REAL L1, L2, L3 , L12 , L250 , MAG(513) , PER(350)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      SET FLAGS NW TO ZERO ROR SUBROUTINE V3CONT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        **S = SLIP **TO BE ITERATED LATER
                                                                                                                                                                                                                                       **1** INSERTION-----
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                IS THE PLOTTER FLAG FOR E 2ND, 3RD, , AND 4TH PLOT.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       = 2.0 . AP / 3.0
                                                                                                                                                    COMPL EX X0(544)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             VALUES -
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   257= 12** 2.6
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                2540(5,106)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             R4= ~ 3* (1.)
RT=&3+R2+R4
                                                                                                                                                                                                                                       SECTION
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   CU22=0.0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             K
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                X=24 3
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H

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CALL PKFOUR(NINT, Y)X,GA,PE,KX,H,ZZ1,ZZ2,ZZ3,TIME,PNTS,KEEP,IFL)
If(If(4)) 2,4,5
                                                                        C ***IPNI # C HERE IF SUMMARY 3JRVES ARE DESIRED*****
                                                                                                                                                                                                                                                                                                                                                                                                                                                                  *** NCC # 1 , PORTION OF PIONTS RELEASED TO SECTION 5-
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               * NUMBER OF INTESRATORS --- ***----
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         C ** GA * GAIN OF INTEGRATER **********
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         BERLINALE BINION JUNE SECRETARIOS EN FINA
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      ** SECTION ** 3 ** INSERTIONS *******
                                                                                                            C***NPLN = NUMBER OF RUNS TO BE 41DE ---
C. .. VH . PEAK VOLTAGE -----
                                    VM = V" SORT (2.0) / SORT (3.0)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     C** SECTION ** 2 **INSERTIONS
                                                                                                                                                                    MECN
                                                                                                                                                                                                                                                                                                                                                                                                                           = -1.256789
                                                                                                                                                                                                                                                                                                                                       [FL(2) = -1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   301
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-- HT -- IS BETWEEN SIX AND EIGHT PI OUTPUT DATA--
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     IF(TIME.GE.FINIM.OR.PNIS.GE.PT4K) ISTOP = 1
IF ((IPR+ISTOP).E1.3) GO TO 11
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X(8)=RX2*Y(T)/L12-V3T*L2/L12+R2*(Y(8)-Y(9))
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           X(1)= V1T -K1*Y(1) +F2*(Y(3)-Y(2))
X(2)=DX2*Y(1)/L12-V1T+L2/L12+R2*(Y(2)-Y(3))
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              X(4)=V2T-R1*Y(4)+R2* (Y(6)-Y(5))
X(5)=PX2*Y(4)/L12-V2T*L2/L12+R2*(Y(5)-Y(5))
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                CUR1 V TOTAL CURRENT FOR PHASE ** 1 **
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          NN FLAG FROM V3CONT IS SET (1)
                                                                                                    OPT=1 PHONE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                      K(9) = R2*Y(6) - RT*Y(9)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 SECTION .. 4
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TIME FOR ONE CYCLE # 1/50 SHUDAUS ARRESTERMENTARESTERMENT
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 ***************
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          9RE(I)9RIM(I)9MA3(I)9FREQ(I)9PE2(I)9I=19NX
X9E14-795X9E14-795X9E14-7795X9F8-335X9F8-3)
                  SALL AXIS(f., to, toHPI RADIANS, -10,8., 6., 0., 0.25)
                                                     CALL AXIS(U., U., 11HVOLTS (L-N),11,50,900,A1,A2)
                                                                                                                                                                                                                                                                                     ., C., 4 HA4PS, 4, 6, , 90., -35., 11.56)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    445(I)=((RE(I)++2)+(RIH(I)++2))++3.5
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         ( .. + (MAG(I) / MAS(2))
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 ONE CYCLE = 2 PI RADS
                                                                                        CALL LINE (W11, AC1, NF, 1, 25,2)
                                                                                                                          CALL LINE (HT1, AC4, NF, 1, 25,5)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                CALL FFTCC (XO,NF,IMK,WK)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    IF (M. En. 8) 60 TO 48
                                                                                                                                                             (: ., 6., 3)
                                                                                                                                                                                                                                                                                                                       PLOTE(N)
                                                                                                                                                                                                                                                                                                                                                           10 20 I=1,NF
XO(I)=AC4(I)
                                                                                                                                              "3", "TNIca
                                                                                                                                                                                                                                                                                                       PLOT (1
                                                                                                                                                                                                                                                                                                                                                                                            BUNITACO
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                CONT INUE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    260
5 N
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CALL PLOT (0.,0.,-3)

SYMBOLIS REFERENCE HAP (R=1)

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12/22/86 10,10,16
SUBSOLICE REFORE 74/74 OPT=1 PHOHP
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SUBROUTINE FKFOUR(N,Y,X,GAIN,PEAK,KX,H,C1,C2,C3,TIHE,PNTS,KEFP,FL)
QIMENSION Y(20),X(2),GAIN(20),EAK(20),KX(4,20),
BH(9),C1(20),C2(20),C3(20),A(3)
INTEGER FL(7)
DATA A(1)/C.1/,A(2)/A(2)/A(3)/1.0E8/,A(4)/1.4414214/,A(3)/1.13E-4/
DATA A(1)/C.1/,A(2)/A(3)/A(3)/1.0E8/,A(4)/1.414214/,A(3)/1.13E-4/
DATA A(5)/1.CE-2/,A(7)/0.0/,A(8)/3.6/
                                                                                                                                                                                                                                                                                                                                                                                                                                                          IF(FL(2)) 31,33,33
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            IF(FL(2)-3) 26,60,6
IF(FL(3)) 21,36,22
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               IF(FL(2)) 31,40,45
FL(5)=KEEP
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             IF (FL (3)) 25,3(,2)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       [F(1-H(1)) 4,30,4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     F (7-H(3)) 4,4,24
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          [F (7-H(2)) 23,4,4
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  IF (3-H(1)) 4,30,4
                                                                                                          IF(FL(1)) 1,3,20
00 2 I=1,N
                                                                                                                                                                                                                                                                                                                                                                                                                                              IF(CL(1)) 6,6,19
                                                                                                                                                                                                                                                                                                                                                                                                  C2(I) =6AIN(I) *0
                                                                                                                                                                                                                                                                                                                                                                                                                              3 (I) =C2(I) /6.0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          XX(1, I)=XX(3, I)
XX(2, I)=XX(4, I)
                                                                                                                                                                                                                                                                                                                                                                                                             C1 (I) = 4.5 · C2 (I)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          PNTS= DNTS+1.0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       DD 3 I=1,N
XX(3,I)=Y(I)
XX(4,I)=X(I)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     0=+(1)+H(4)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            00 32 I=1,N
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           0=4(1)/H(4)
                                                                                                                                                       DE4K(1)=0.0
                                                                                                                                                                    GAIN(I)=1.0
TIME=0.0
                                                                                                                                                                                                                                               FL (1) = 0
00 3 I= 19
                                                                                                                                                                                                                                                                                                                                     FL (7) =H(8)
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  H(9)=TIME
                                                                                                                                                                                                                                                                            H(I) = A(I)
                                                                                                                                       V(I) = 2.0
                                                                                                                                                                                                                  FL (4) =-1
                                                                                                                                                                                                  PATS= 9.6
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               J= (2) T
                                                                                                                                                                                                                                                                                            ひに しにいる
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    FL (4)=1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 Natified
                                                                                                                                                                                                                                FL (5) =1
                                                                                                                                                                                                                                                                                                                         FL (4) =1
                                                                                                                                                                                                                                                                                                                                                                     FL (3) =5
                                                                                                                                                                                                                                                                                                                                                                                                                                                                             FL (1) =1
                                                                                                                                                                                                                                                                                                           0=H(1)
                                                                                                                                                                                                                                                                                                                                                      4(1)=0
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        7±H(2)
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SIIBROUTINE V3CONT (ALP, Y, V1T, V2T, V3T, HT, HTAP, HTAM, NN, PNTS)
                                           SURROUTINE VECONT IS THE VOLTAGE CONTROLLEF

-- V -- IS THE AKWAY OF CURRENTS FROM SUBROUTING RKFOUR

THE -- NN -- ARRAY ARE THE FLAGS FOR THE THREE VOLTAGES

-- PNTS -- IS THE CUIPUT COUNTER FROM RKFOUR

ALP IS ANGLE IN RADIANS FOR VOLTAGE TO BE ZERO
                                                                                                                                                                                          EACH CONTROLLER VIT , V2T, V3T , 43RKS INDEPENDENTLY
And are identical in logic
                                                                                                                                                                                                                                                                  serestates CONTROLLER FOR VIT estatetates
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                SAMPLE CURRENT ONE TO CHECK FOR ZERO CROSSING IF TRUE SET FLAG NN(1) = 1

IF(91.61...11)GO TO 3
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             *********
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          IF(PNTS.LT.NN(F)) GO TO 3
91 IS THE ABSOLUTE VALUE OF CURRENT --Y(1)
81=A9S(Y(1))
                                                                                                                                                                                                                                                                                                                 IF THE SOR IS SHUT OFF THEN NN(2) = 1
SET VOLTAGE AND CURRENT EDUAL TO 3.0
                                                                                                                                                                                                                                                                                                                                                                                                                                         HIS IF STATEMENT ALLOWS THE CURRENT TO HOVE AWAY FROM RERO ONCE THE SCR IS TURNED ON
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        GO TO PHASE TWO VOLTAGE CONTROLLER
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         CONTROLLER FOR V2F
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   SET VOLTAGE AND CURRENT TO ZERD
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             THE TI TIMER IS SET FOR PERIOD THAT THE SCR IS TO STAY OFF
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          --WILL BE FALSE
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       SET FLAG NN(1) = 0 TO INDICATE THE SCR IS TURNED ON
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                       RESET POINT COUNTER NN (4)
                                                                                                                                                                                                                                                                                                                                                                                           IF (NY (1). En.1) GO TO 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  F (WT .6T.T1) GO TO 2
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                            4N(4) # PNTS + 60
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              STATEMENT -- 1
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             *********
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         (1)=1.6
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59

F.P. 0000 ARZAY REALL REALL REALL REALL REALL 31 33 PNTS 72 V11 V3T \*\*\*\*\*\*\*\*\*\*\* CONFROLLER FOR V3F F(0415.LT.KN(5)) 60 TO T=(A3.6T.C.1C) GO TO 9 F (92.6T.0.10)60 TO 6 3= HTAH + ALP F(HTAH.GT.13) GO TO RELOCATION F.P. F (WT 40.6T.T2) GO TO F.P. . . . . . . . . 1 INTRIN 2= ABS(Y(4)) SYMBOLES REFERENCE MAP (R=1) ARRAY INLINE FUNCTIONS ENTRY POINTS 3 V3C3VT 7,5 8 60

REAL	N,IWK(1) WK(1)	FF10159
COMPLEX	A(N)  A(N)  A(N)  A(N)  A(N)  A(N)  A(N)  A(N)	FF 19 17 10
INTEGER	I, IAH, IAP, IBH, IBP, IC, ICC, ICF, ICK, IM, ID41, II,	FFTP4730
₩ 84	HIANTANIKAN TELITATIKAN TENITANIKAN TENITAN TAN TAN TAN TAN TAN TAN TAN TAN TAN	FF 10.7
	KT,KTP,L,L,L,L,LL,LL	FFTP37
PEAL	CH, SH, G1, G2, 33, S1, S2, S3, G3C, RAD, A7, A1, A4, 94,	FFT017
- n	A C 9 A C 9 3 L 9 3 L 9 3 L 9 3 L 9 C 6 K J 9 MA L F 9 D N E 9 L 4 D 9 / C ( C ) 9 H 4 / C 0 L 1 2 2 C 0 J 7 4 / C 0 L 1 2 C 0	FF (P.4/2
XS TOHOU	740.241.742.783.744.472	FFTD19
ENCE	(ZAU, ZU(1)), (ZAL, Z1(1)), (ZA2, 72(1)),	FFTP38
	(ZA3, Z3(1)), (63, 76(1)), (Bf, 71(2)), (A1, 71(1)),	FFTP.3
<b>~</b> '	(81,71(2)), (42,72(1)), (82,72(2)), (43,73(1)),	FFTP18
•	(83, 23(2)), (244, 24(1)), (24(1), 44), (24(2), 94)	FF19,96
DATA	RAD/6.2831853471796/	FFTP195
1.03.78	U.S.U./ • 8.668.2944.67.944.47.47.97.67.	FETO'S
DUTINE NAME		FF TO SE
		FFTP16
		OLGLISH-
		FFTP
COMPUTER	- COC/SINSLE	THE TOTAL OF THE
LATEST REVISION	- JANUARY 1. 1973	FFTP131
		FFTD108
PURBOSE	- COMPUTE THE FAST FOURIER TRANSFORM OF A	<u> </u>
		FFTP)1C
115A F. F	(ME.MET. 2.42 COTTO	FFTP1120
		FFTP1130
ARGUMENTS A	OF LEAGTH N. ON IVPUT A	
	CONTAINS THE SOMPLEX VALUED SETUENCE TO BE	L.
	RMED. DN OUTPUT A IS REPLACED BY	
	FOURTER TRANSFORM.	FF To 117
Z	DE DATA POINTS TO SEL	FFTFTTPT
	20	1 1 1 1 1 4 C
T X	AK VESTOR OF LENGTH 6"4+159	FFT0221
	(SEE PROGRAMING NOTES FOR FURTHER DETAILS)	FFTF:220
¥	- REAL MORK VESTOR OF LENGTH 6*N+110.	FF TO 12
	(SEE PROGRAMING NOTES FOR FURTHER DETAILS)	FFFF12
REPORT TO THE REPORT OF THE PERSON	STAGE	FF 15 25.0
HERBERT TO TOTAL	SIZGLE/THE CONTRIBUTE	FFTP 21
		FFTP:26
REDD. I PSL ROUTINES	S - NONE REJUITED	FFT01200
	CAM SCITISTICA LATERACA SO NOTITION OF A	THID WAS
		FF 10, 323
	INTRODUCTION OR THROUGH INSL ROUTINE UMELP	FF1P0330
		FF 1P13t

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FELD13T
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                                                                                                                                                                  FFTP-18
                                                                                                                                                                                                             FTPJIFE
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                                                                                                                       FFTP142
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                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                              DETERMINE THE REMAINING FACTORS OF N FFTPLS
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        FIETEL
                                                                                                                                                                                                                                                                                                                                                                                                        - IMSL WARRANTS DN_Y THAT IHSL TESTING HAS PEEN
APPLIED TO 141S CODE. NO OTHER WARRANTY,
EXPRESSED DR IMPLIED, IS APPLICABLE.
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     z
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    DETERMINE THE SQUARE FACIORS OF
                                                                                                                                                                                                                                                                                                                                                                             - 1978 BY IMSL, IND. A.L RIGHTS RFYERVED.
                                                                                                                                                                X(K+1) = (1/N)*SU4 F43H J = 6 T0 N-1 OF
A(J+1)*CEKP((0.(9(-2.(*PI*J*K)/N)))
                                                           X(K+1) = SUN FROM J = 0 TO N-1 OF
A(J+1)*CEKP((L.)*(2..*PI*J*K)/N))
FOR K=0,1,...,V-1 AV) PI=3.1415...
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                             FIRST EXECUTABLE STATEMENT
                                                                                                                                                                                             FOR KRG, 1, ..., N-1 AND PIES-1415 ...
                                                                                                                    NOTE THAT X OVERWRITES & ON OUTPUT. FFICE CAN BE USED TO SCHPUTE
                                                                                                                                                                                                                          BY PERFORMING THE FOLLOAING STEPS:
                                                                                                                                                                                                                                                                                                                                A(I) = CONJGIA(I))/N
                                                                                                                                                                                                                                                                                                 CALL FFICE (A,N,IAC,HK)
                                                                                                                                                                                                                                                       DO 1D I=1,N
A(I) = CONJG(4(I))
                                                                                                                                                                                                                                                                                                                   00 20 I=1,N
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 GO TO 10
                                                                                                                                                                                                                                                                                      CONT INVE
                                                                                                                                                                                                                                                                                                                                               CONTINUE
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FFT01150 FFT01160 FFT01173 FFT01193 FFT01193			######################################		A
G0 T0 15 J = J + 1 IF (J • E0 • 3) J = J + 1 IF (J • LF • K) G0 K = TWK (H+1)	- Y NOTHER	TOOS TO THE TOO TO THE TOO TO THE TOO TO THE THE THE TOO TO THE THE TOO TH	K II	11	INV(IC) = 1 INV(IC) = 1 DO 45 J = 1,4 DO 45 J = 1,4 INV(IC+1) = INV(IC+J-1) * K INV(ID+J) = INV(IC+J-1) / K MK(TRD+J) = RAD/INK(IC+J) C1 = RAD/K IF (K *LE* 2) GO TO 45 MK(ICC+J) = COS(C1) HK(ISS+J) = SIN(C1)

FFTP18.0 FFTP1763 FF1P1790 FF 10221 FF1P1759 CE 16118 FFTP1310 FFT 61923 FFTP1930 PETOL34 FFTP136 FFTP13.0 FF TP1318 FFTP21,0 FFTP2116 FFTP13E FFTD130 EFTP312 FFT5219 FF TP185 FFT0132 FFT0134 F 1P19E FFTD213 FFTP222 FF TO225 FFTP197 FFTF133 FFTP135 FF TD22 FACTORS OF 2, 3, AND 4 ARE HANDLED SEPARATELY. (INK(ILL+I+1) .Eq. 1) GO TO 68 \* NK(IRD+H) .LT. KB) GO TO 190 .to. 1) GO TO 85 A(K2+1) = A(KL+1)-AK2 A(KB+1) = A(KI+1)+AK2 A(K)+1) = A(K(+1)+7A0 ú6 210 22% 195 202 13 64

1. *E0. 1) GO TO 103  44.C1+4.51  44.C1+4.51  44.C1+4.62  14.S2+4.62  14.S2+4.62  14.S2+4.62  14.S2+4.62  14.S2+4.62  14.S2+4.62  15.S2+4.S2  16.S1  17.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S2  18.S2+4.S3  19.S3+4.S3  19.S3+4.S3  19.S3+4.S3  10.S3+4.S3  1	원 원 원 경 분 수 1 대 전 1 나 전 1 + 1	+81+30) +81+80) +81+80) +81+80)	+81+33																			155 +164 +164 +164 +164 +164 +164 +164 +164	-		シップ・ウルドル に	E de carre											
2	72-1) = CMPLX(AU-AZ-81+33,81-9Z+AZ-81+1) = CMPLX(AU-AZ-81+33,81-9Z+AZ-81-BZ,81-BZ-AZ-81-BZ,81-BZ-AZ-81-BZ-AZ-81-BZ-AZ-8Z-AZ-AZ-AZ-AZ-AZ-AZ-AZ-AZ-AZ-AZ-AZ-AZ-AZ	4( kg+1) = CMPLX(AG+A2+A1+A3,BC+32 4( k1+1) = CMPLX(AG+A2-A1-A3,BG+32 4( K2+1) = CMPLX(Au-A2-B1+33,B1+32 4( ki+1) = CMPLX(Au-A2+B1+33,BC+92	743 = A(K3+1) 4(Ky+1) = CMPLX(A6+A2+A1+A3+36+32	741 H ACK	30 TO 430	0 + 40 + 10 + 41	٠.	 4	¥.	** S1+84*	* 45-13 . 4	A(K1+1)	A(KL+1) . • E0. 1) GO TO 12	1 + 2	+ + + :	A - 11 +	= JM+1 135 II = IKR-I	= K8+1	KA + JA + KB	S3 # S1 * G2 + G1 # S	= C1 * C2 - S1 * S	C2 = C1 * C1 - S1 * S	10 10 196 IF (L1 .E0. 1) GO TO 12	CONTINUE	4(K1+1) = CHPLX(AC-R1,9f+A 4(K2+1) = CMPLX(AO+91,8n-A	-82) + C3U	(-A2) = C33 (LF * (81+82) +	A: = -HALF * (A1+A2) + A	A ( Ku +1 ) = CHP	7A2 H A(	50 10 1	. A4*52+P4*C	= AlkC+1) : At•(2-04+5	44.81+B4.C	ALTCALPETS	= A(K1+1)	111 . En. 1) 60 TO

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                               FELLOS
                                                   HK (ICF+J+1) = MK(ICF+J) + G1 - M(ISF+J) + S1
HK (ISF+J+1) = MK(ICF+J) + G1
                                                                                                                                                                                                      NK(ICK+J) * S2 + HK(ISK+J) * C2
                                                                                                                                                                                 MK(ICK+J) + 32 - AK(ISK+J) * S2
                                                                                                                                                                                                                                                                                                                                                                                              = A4" WK (ICF +K) -84+WK (ISF+K)
                                                                                                                                                                                                                                                                                                                                                                           = A4" WK (ISF +J) +94 + WK (ICF+J)
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GO TO 150
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S2 = WK(ISS+I)
WK(ISK+1) = S2
WK(ISK+JK) = -S2
D0 I'E J = 1,KH
                                                                                   IF (KF .EQ. JF)
C2 = WK(ICC+I)
                                                                                                         MK(ICK+1) = C2
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15 IF (KF .
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160 Ka = Ka
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4(K2+1) = CMPLX(A1+82,81-A2)
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R .GE. KN) 60 TO 215
IWK(IC+I-2) + JJ
                                                                                                                   (KA .6T. KB) GO TO 160 = KF
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South Contract Secretary Contraction

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             FTE 4.0+318
SUNCETTAE PFFCC 74/74 OPT=1 PHOMP
                                                                                                                                                                                      +K(ID+J) + K3
- K8 •GE. IWK(ID+J-1)) G0 [3 250
                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    (JJ .LT. IWK(ID+K)) GJ TO 295
= JJ - IWK(ID+K)
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60 TO 245
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WK(J+1) + I
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                                                                                                                                                                                                                                                                                                         K) G0 T0 255
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		1 # 1 + 1 16 (1 (1 18) GO TO 325		FF TP4950
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<b>9</b> 6	9615	CONTINUE		
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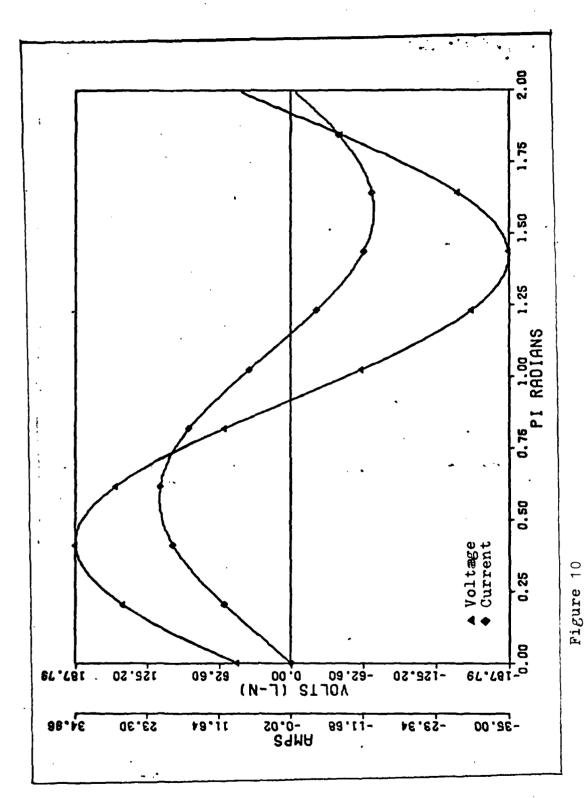
SYMPOLIS REFERENCE MAP (R=1)

Appendix D

Figures of the Reflective

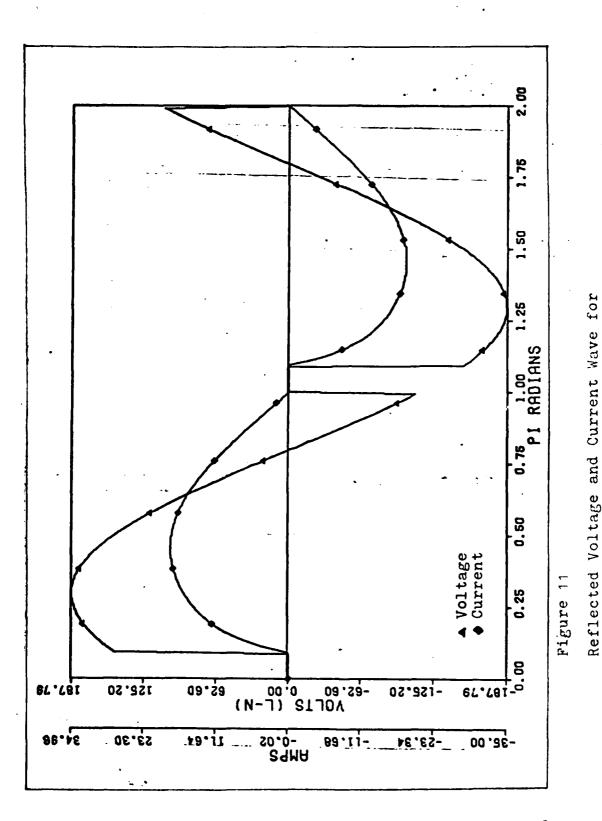
Waves of the Controlled Motors

5 Horse Power Energy Efficient Motor

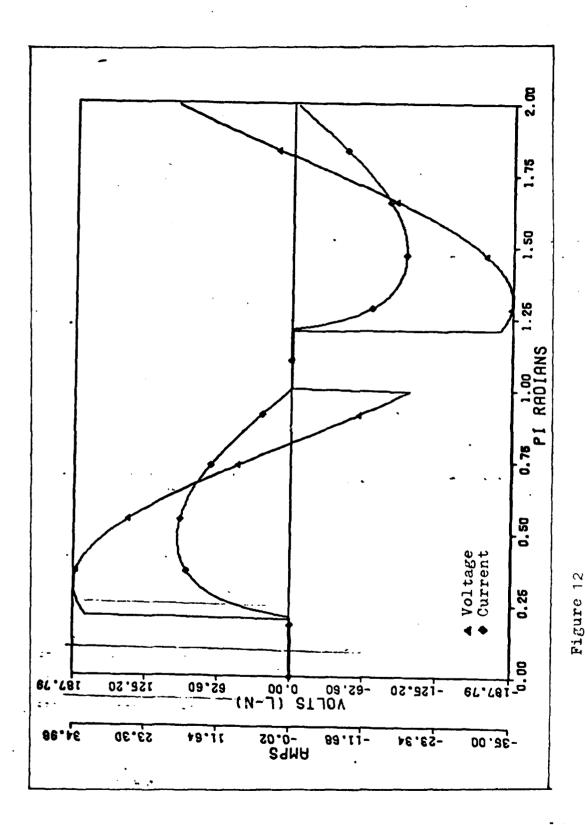


CONTROL OF THE STATE OF THE STA

Reflected Voltage and Current Wave for 5 Horse Power Energy Efficient with ALPHA equal 0.0

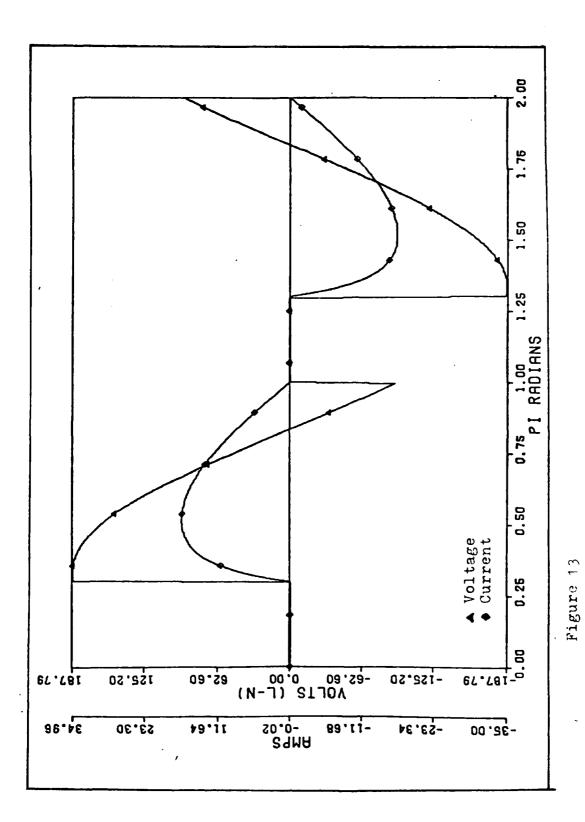


5 Horse Power Energy Efficient with ALPHA equal 0.3

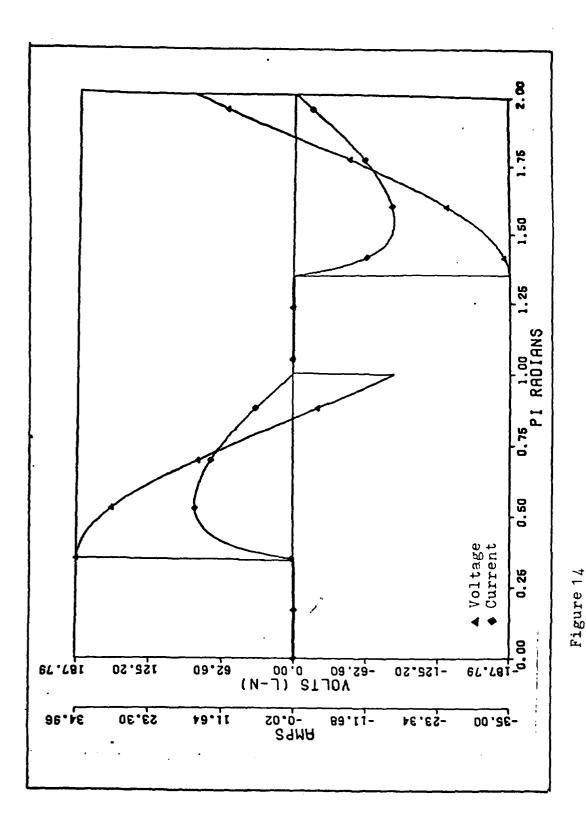


Reflected Voltage and Current Wave for 5 Horse Power Energy Efficient with ALPHA equal 0.65

74

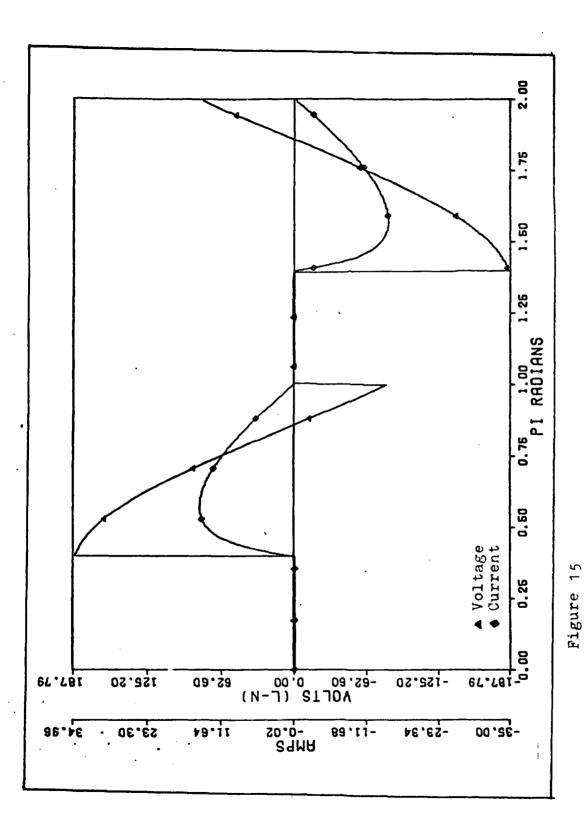


Reflected Voltage and Current Wave for 5 Horse Power Energy Efficient with ALFHA equal 0.95



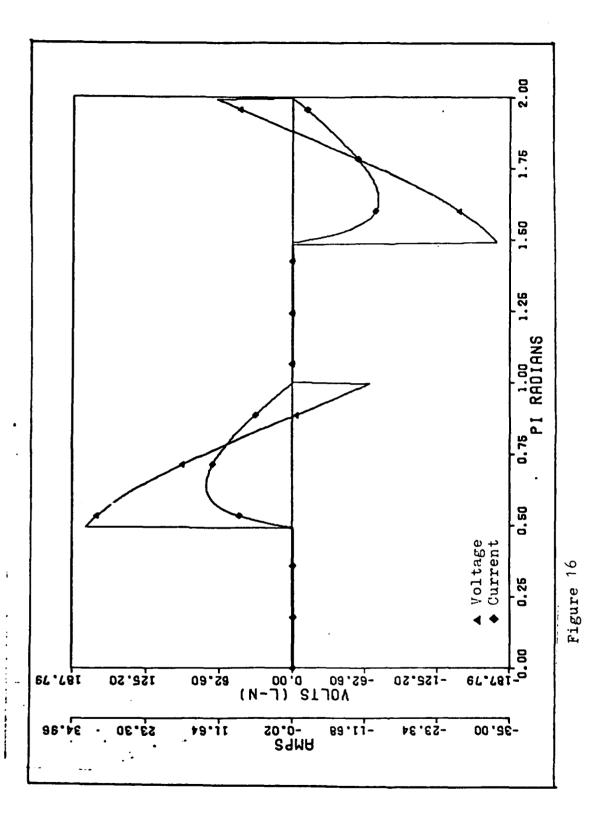
Reflected Voltage and Current Wave for 5 Horse Power Energy Efficient with ALPHA equal 1.10

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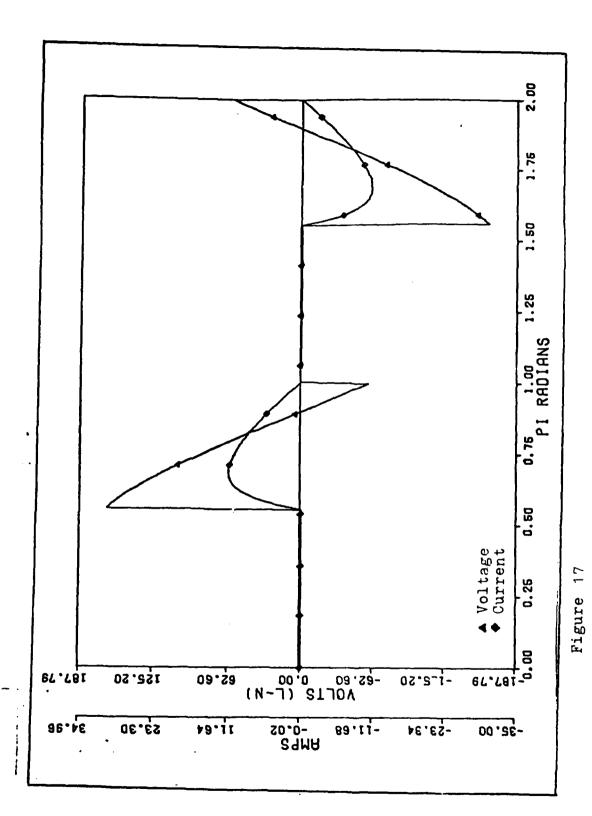
Reflected Voltage and Current Lave for 5 Horse Power Energy Efficient with ALPHA equal 1.3

\$<sup>\*</sup>\$?\$



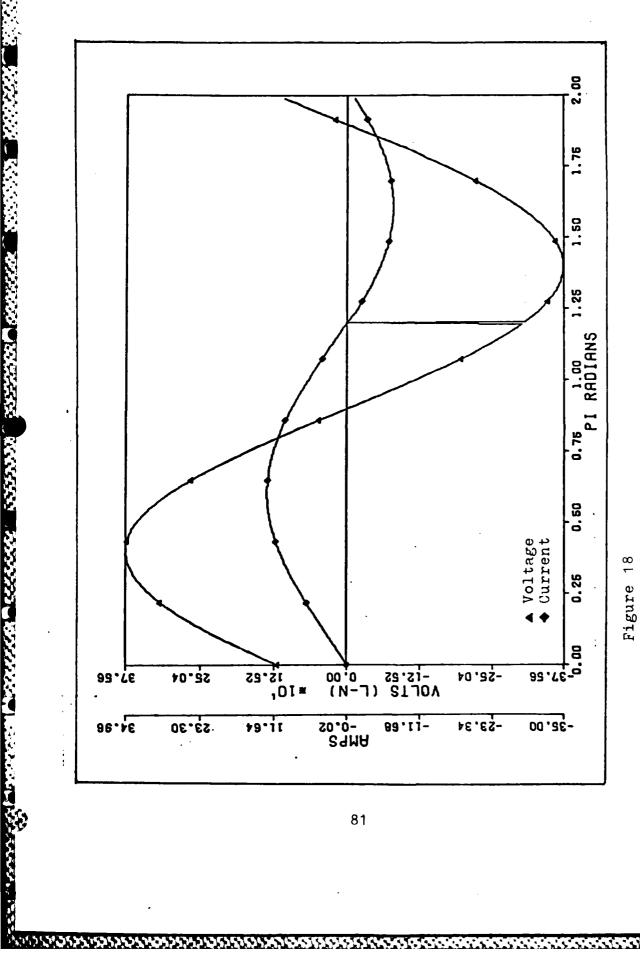
CAST PARTY CONTRACTOR 
The second secon

Reflected Voltage and Current Wave for 5 Horse Power Energy Efficient with ALPHA equal 1.55

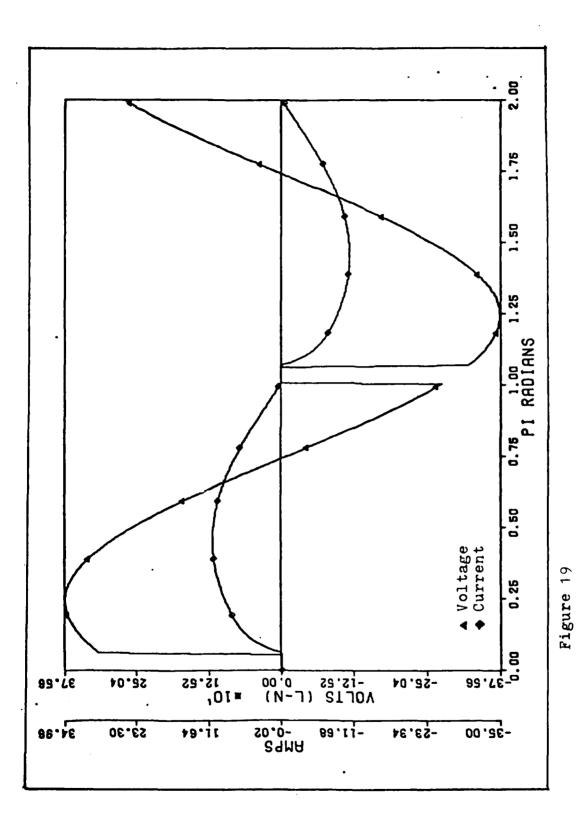


Reflected Voltage and Current Wave for 5 Horse Power Energy Efficient with ALPHA 1.75

5 Horse Power Standard Motor



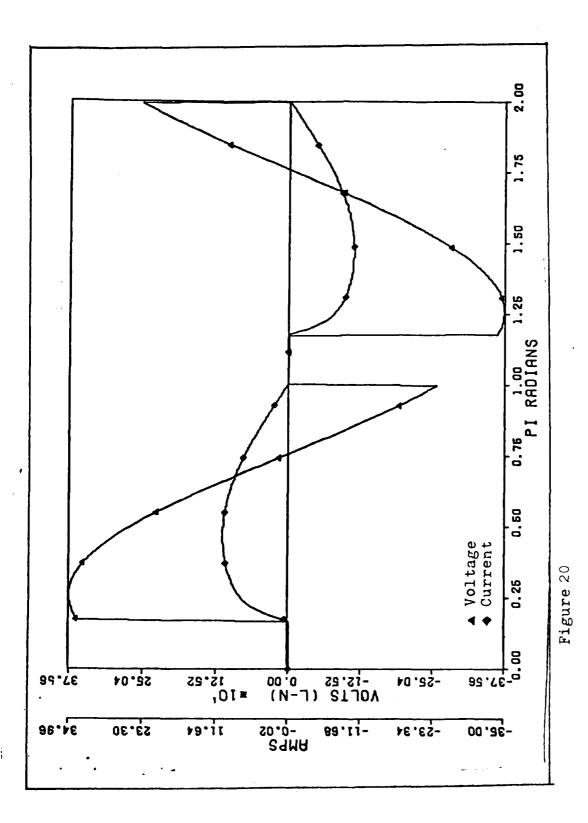
0.0 5 Horse Power Standard with ALPHA equal Reflected Voltage and Current Wave for



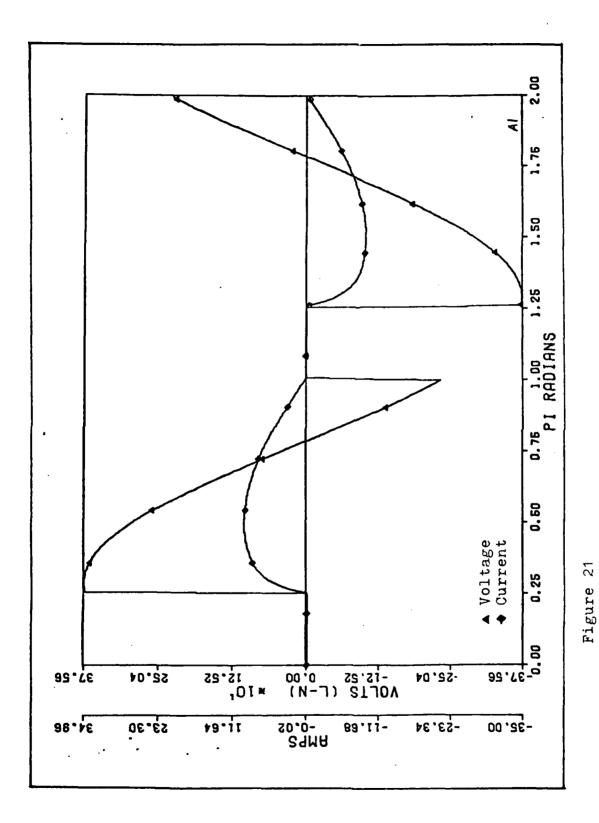
STATE STATESTICK RESIDENCE - PROPERTY CHARGE OF CHARGES

<sup>©</sup>TONY DECEMBER OF THE STATE O

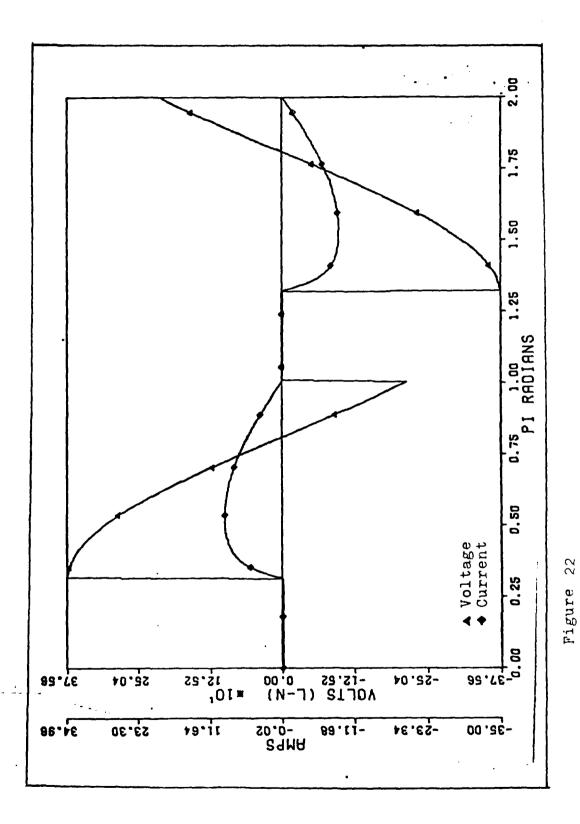
Reflected Voltage and Current Wave for 5 Horse Power Standard with ALPHA equal 0.2



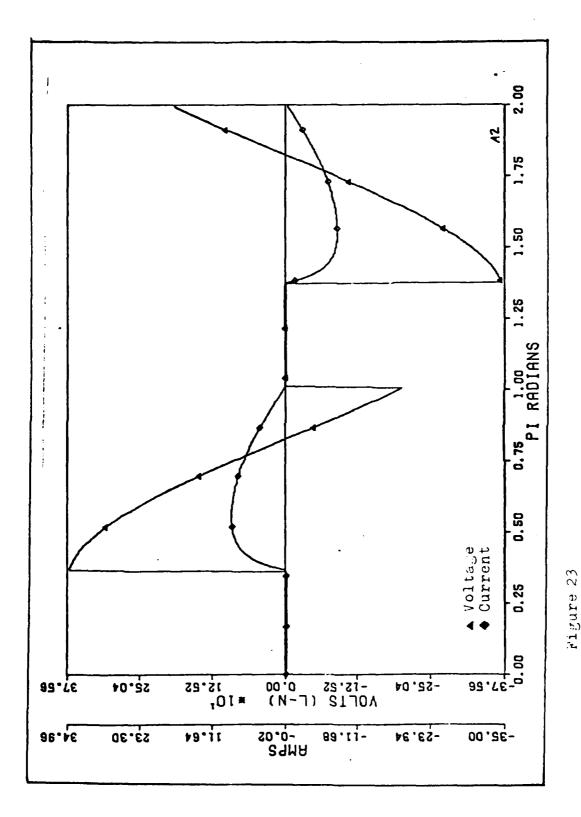
Reflaected Voltage and Current Lave for 5 Horse Power Standard with ALPHA equal 0.55



Reflected Voltage and Current Wave for 5 Horse Power Standard with ALPHA equal 0.8

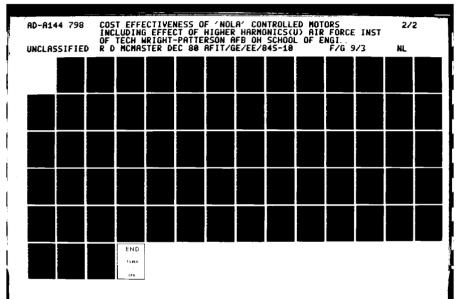


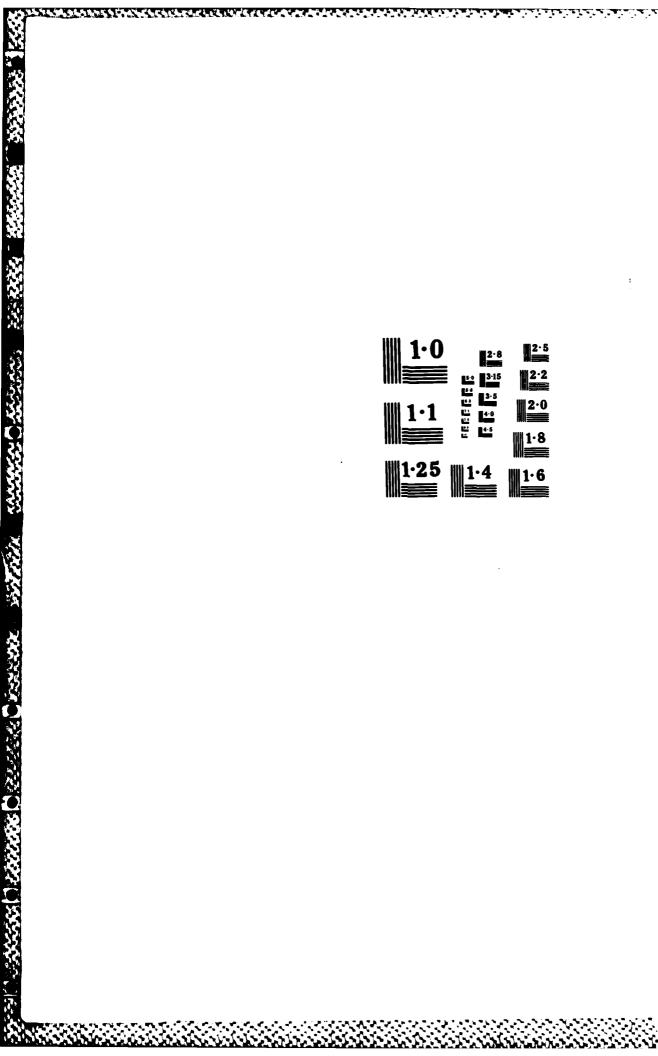
Reflected Voltage and Current Wave for 5 Horse Power Standard with ALPHA equal 1.0

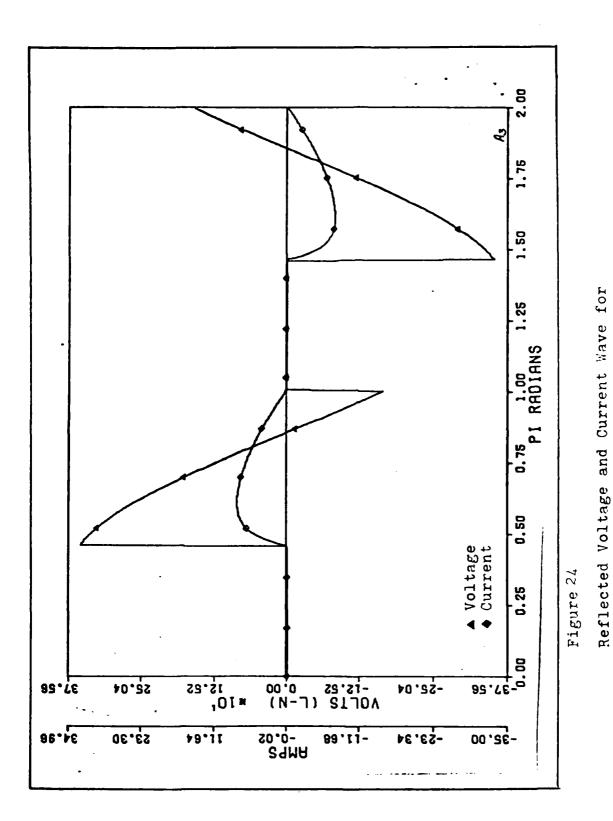


Keflected Voltage and Current Wave for 5 Horse Power Standard witn ALPHA equal 1.15

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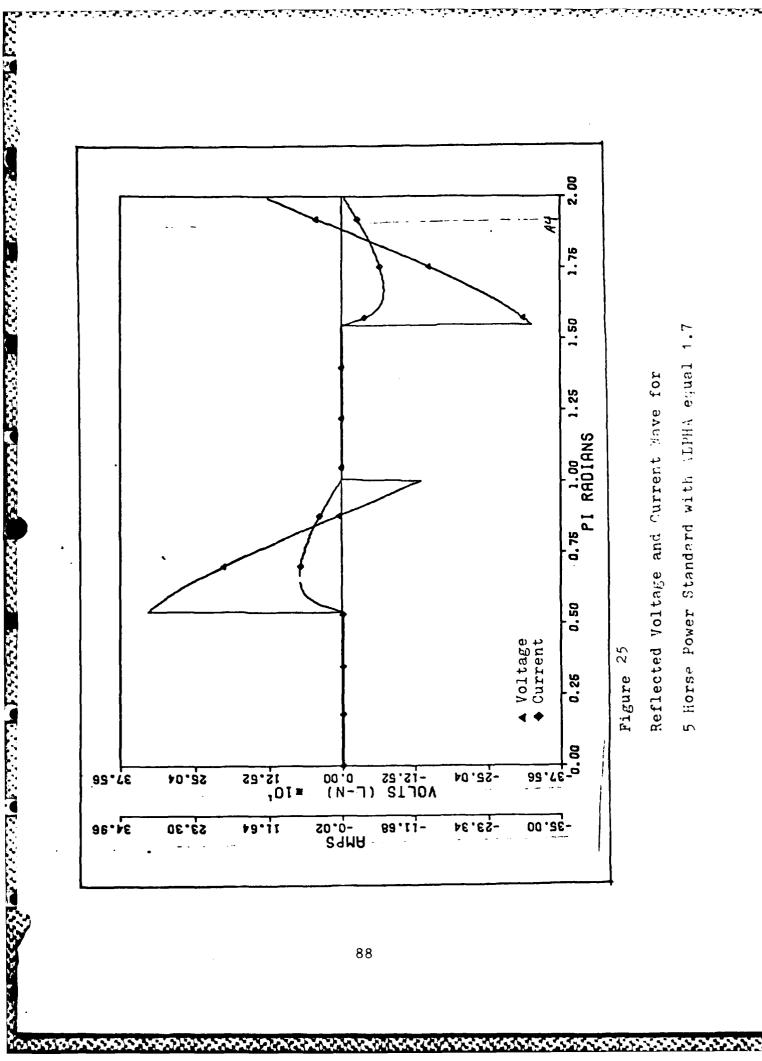




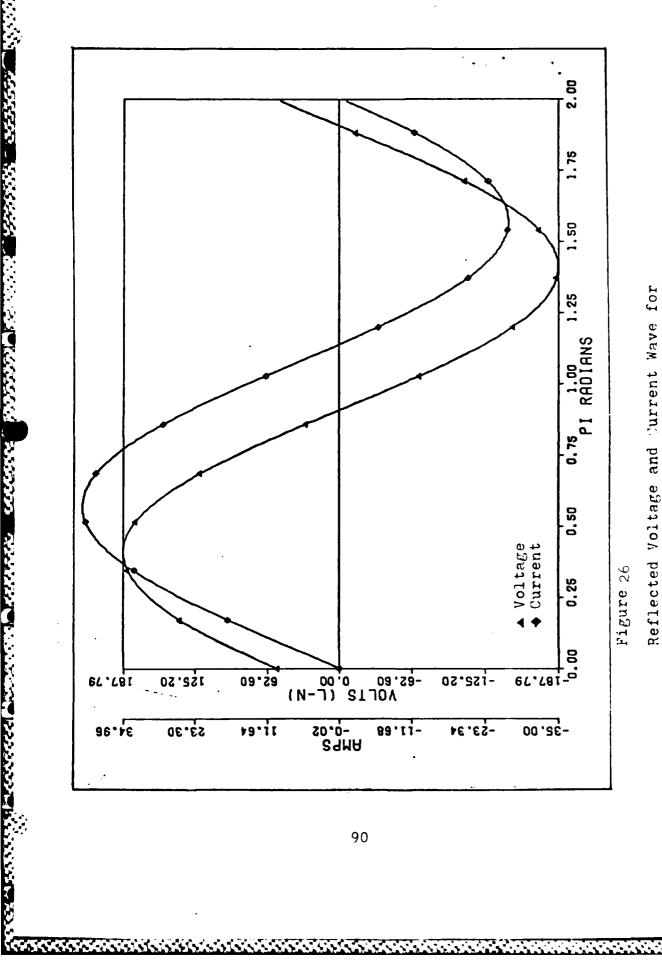


5 Horse Power Standard with ALPHA equal 1.45

87

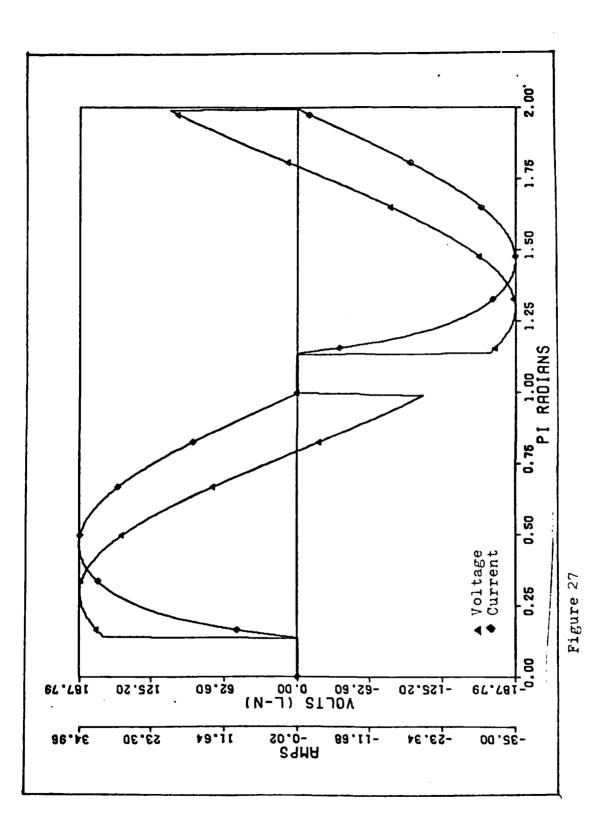


10 Horse Power Energy Efficient Motor



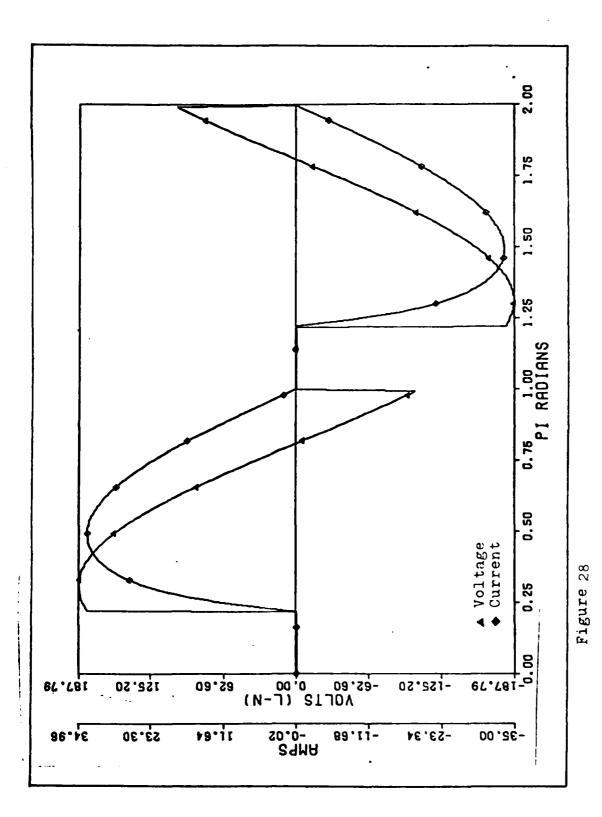
CONTRACTOR OF THE PROPERTY OF

Efficient with ALPHA equal 0.0 10 Horse Power Energy



10 Horse Power Energy Efficient with ALPHA equal 0.45

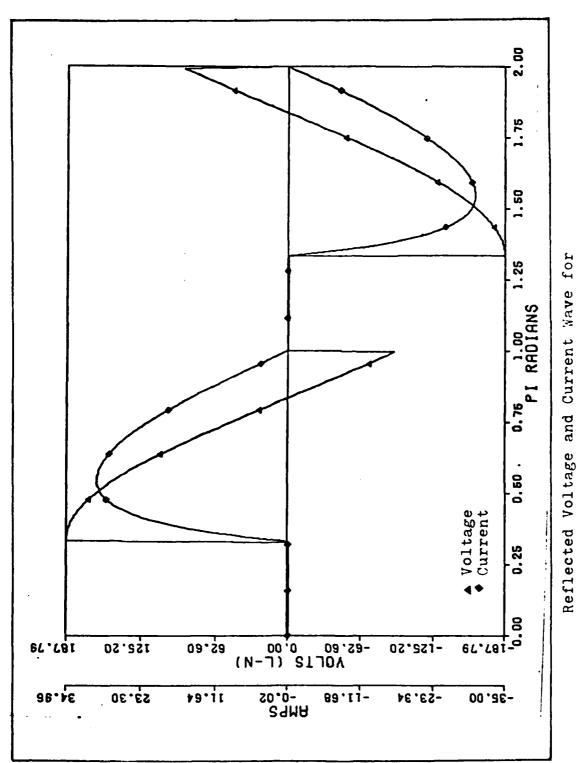
Reflected Voltage and Current Wave for



AND THE PROPERTY OF THE PROPER

Reflected Voltage and Current Wave for 10 Horse Power Energy Efficient with ALPHA equal 0.7

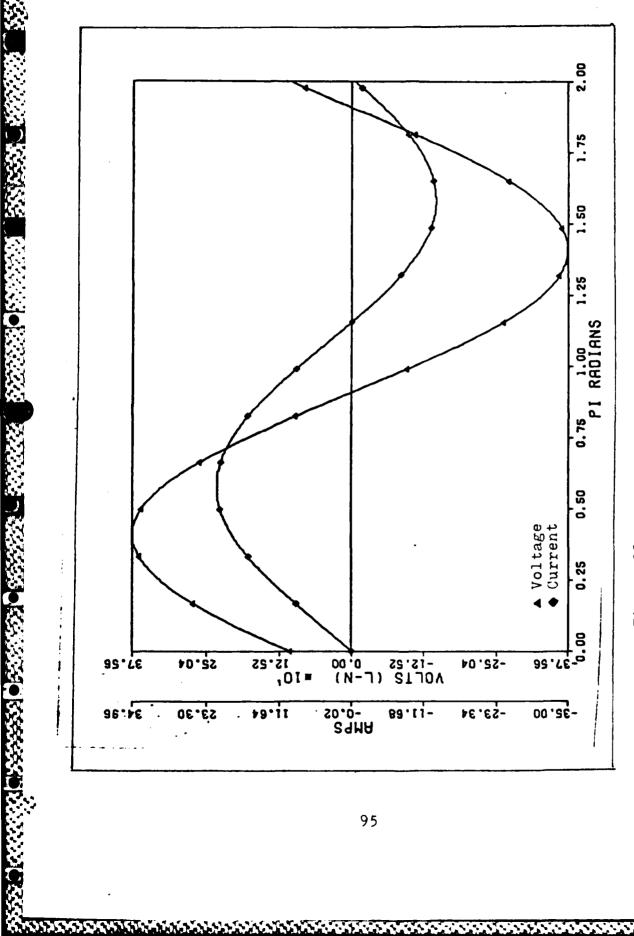
92



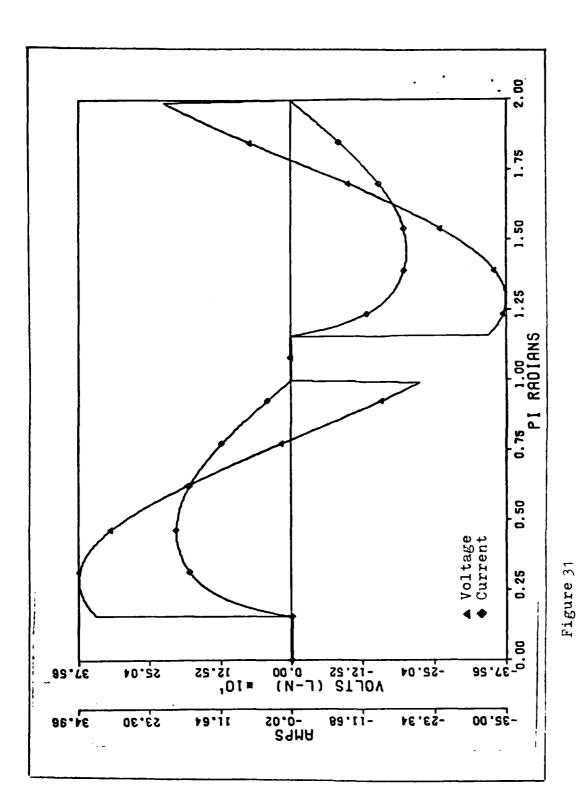
Neitected voices and cuitent maye for 10 Horse Power Energy Efficient with ALPHA equal 1.05

Figure 29

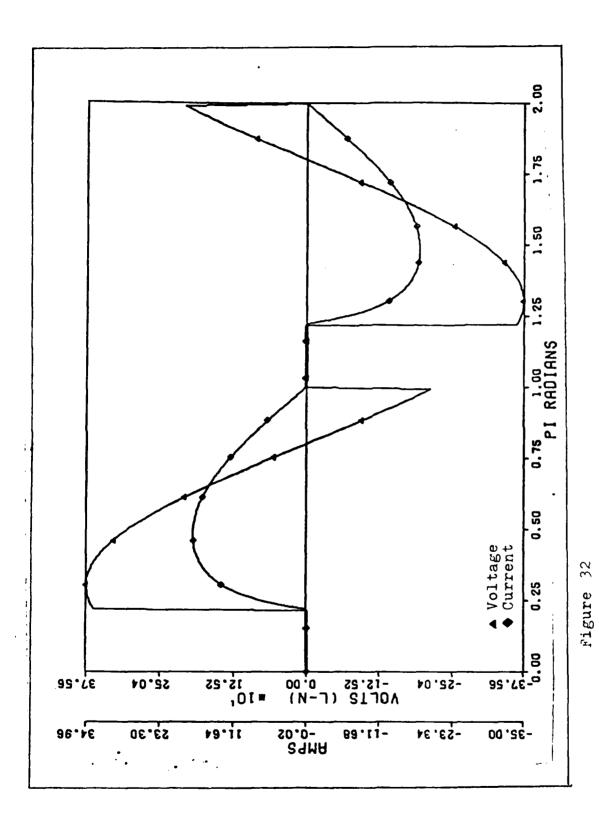
10 Horse Power Standard Motor



10 Horse Power Standard with ALFHA equal 0.0 Reflected Voltage and Current Wave for Figure 30

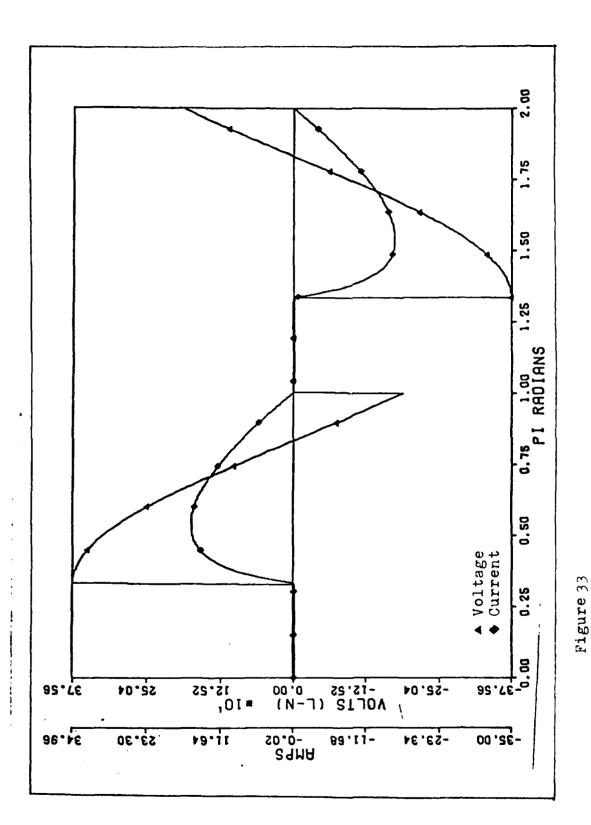


Reflected Voltage and Current Wave for 10 Horse Power Standard with ALFHA equal 0.5

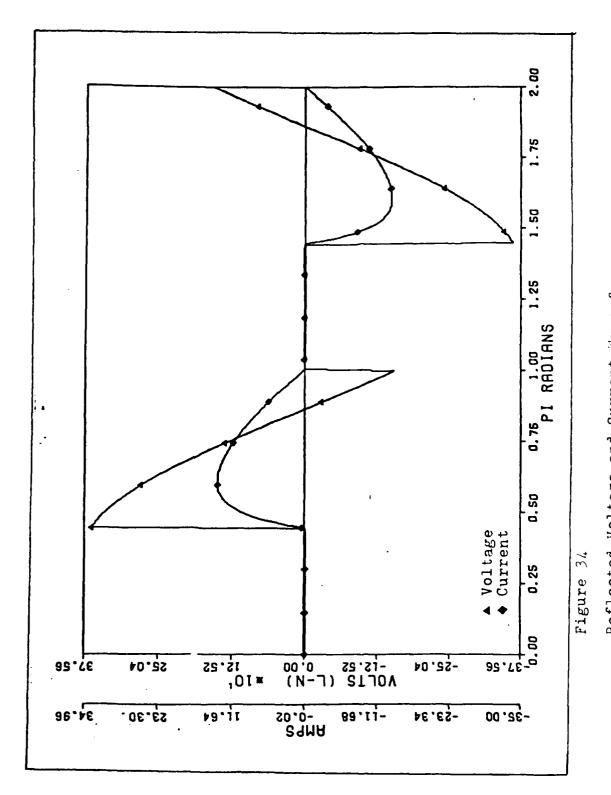


gyviniessyskyj kuzezetet dispisos Dispisos. Papienis (paraete Presente Control Control Control George)

Reflected Voltage and Current Wave for 10 Horse Power Standard with ALPHA equal 0.7

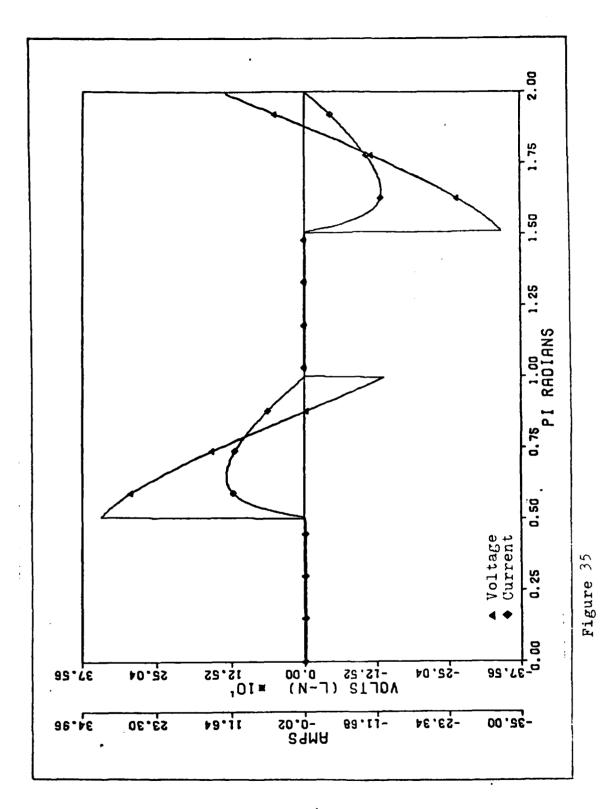


Reflected Voltage and Current Wave for 10 Horse Power Standard with ALFHA equal 1.05

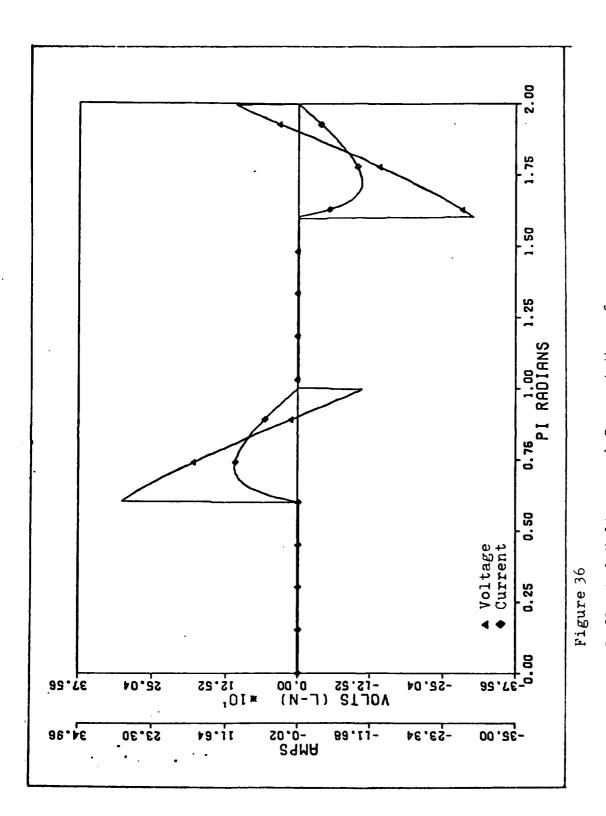


Reflected Voltage and Current Wave for 10 Horse Power Standard with ALFHA equal 1.4

99



Reflected Voltage and Current Wave for 10 Horse Power Standard with ALFHA equal 1.6



Reflected Voltage and Current Wave for 10 Horse Power Standard with ALFHA equal 1.9

Appendix E

Representation of the

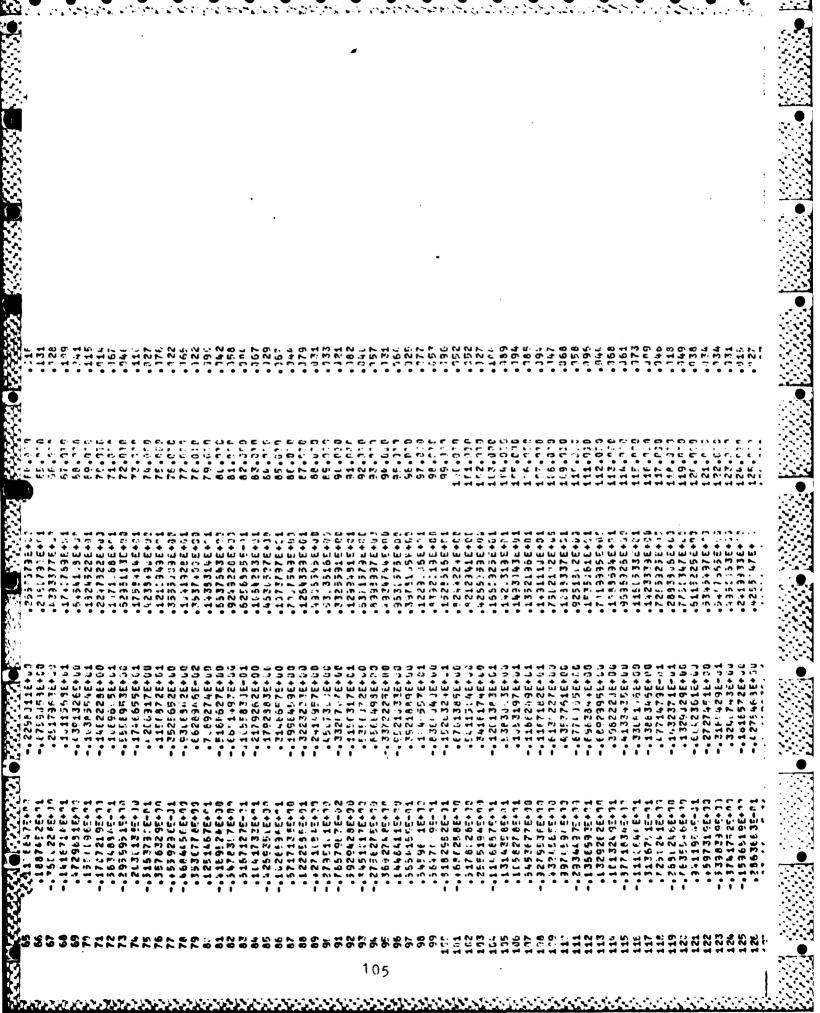
Harmonics Data

From a Fast Fourier Transform

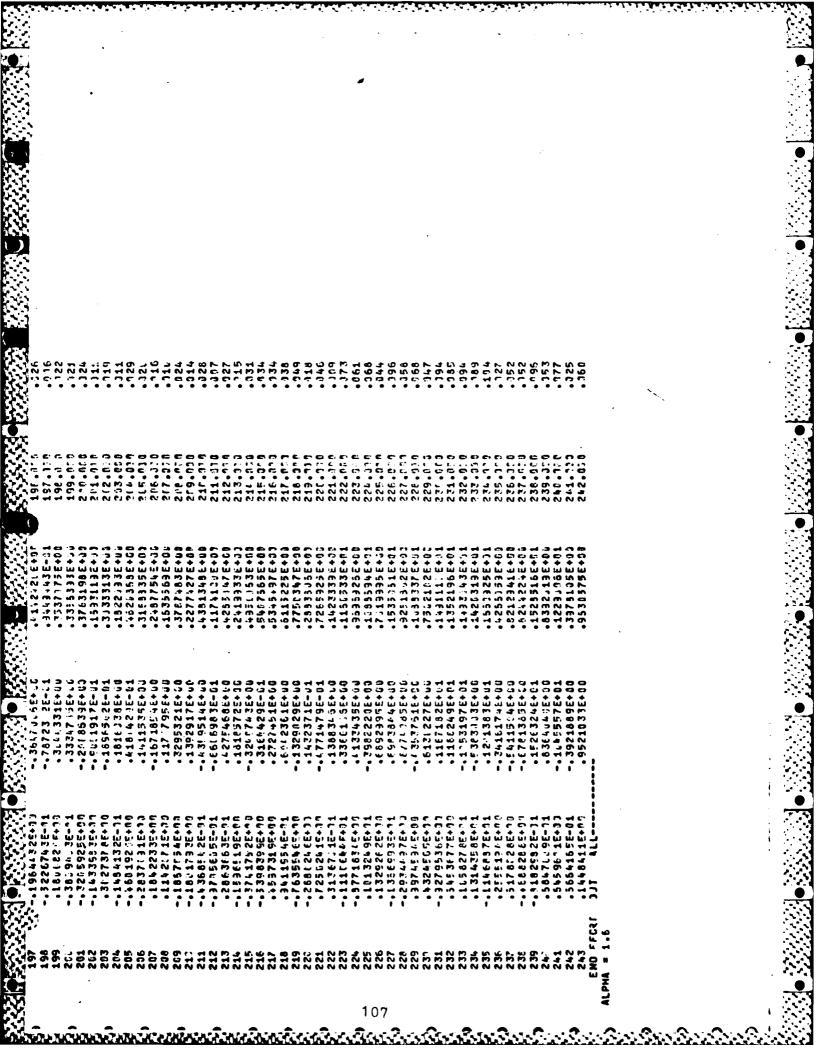
of the Reflected Motor Current

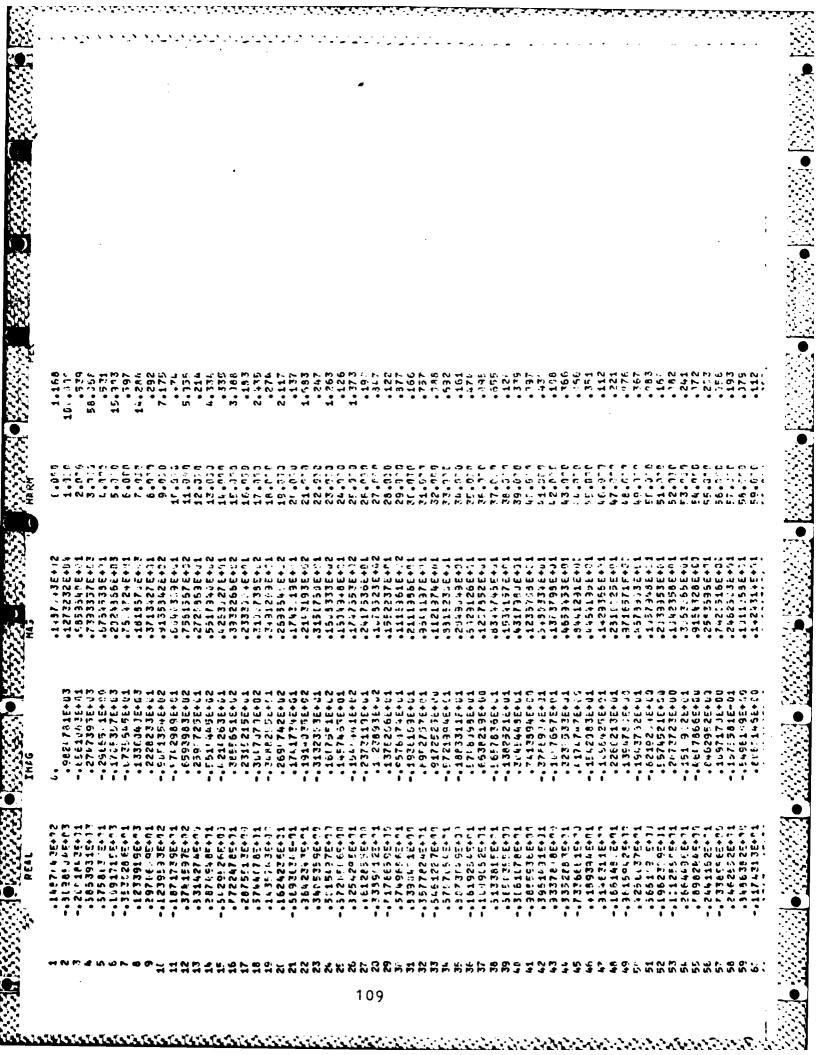
TOTAL SELECTION OF STANDS 070 , CYS , CURT, VITS ,WTS = 2124.614.645982 [ = 2.848: 3496.2443

103

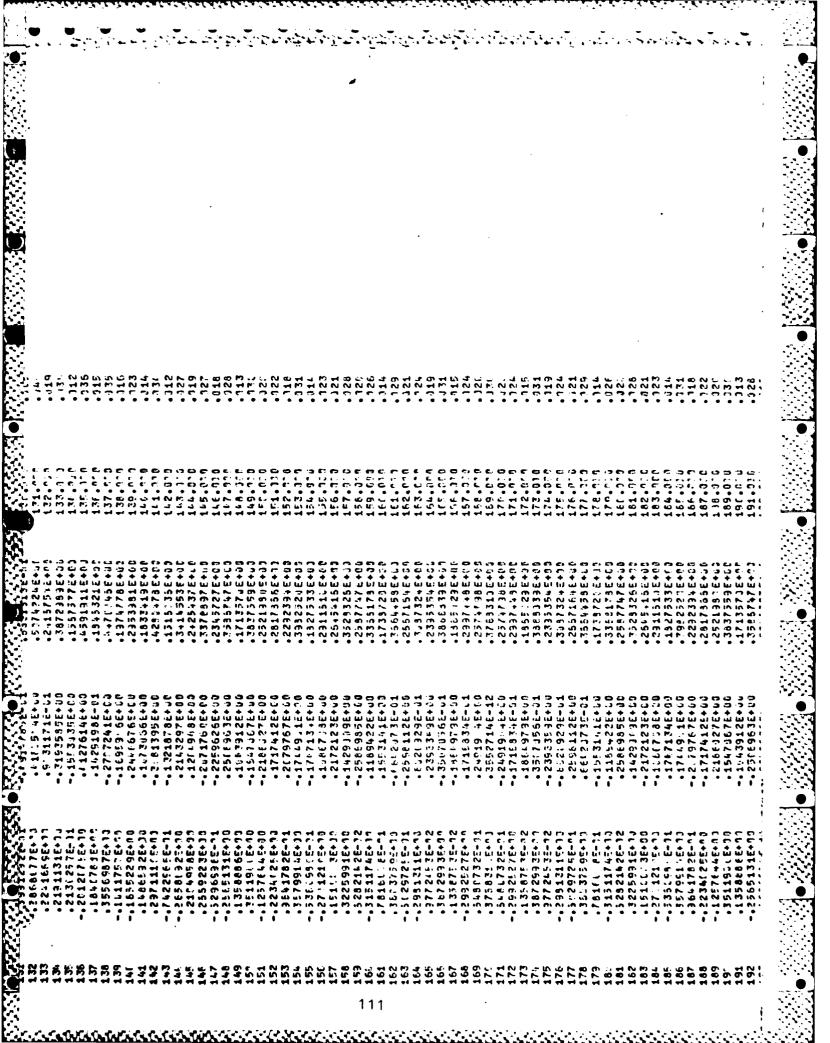


0:00 ) 0 37.03 36.03 Eu ez E.(. . 1) ? 70.01 61.0) ..... .3783199E+00 .3355343E+00 .4527;75E+00 .46.9:23E+0B .3245329E+0B .4.10`14E+03 .9443443E-C1 -0442426E-C1 -365633E-C1 23+5759E+00 3530 930E+03 .4623)16E+0P .3139635E+0B .3213+36E+03 .3175583E+09 .2514395E+34 E+10 .3645324E+03 .8932:55E-u1 2333451E+UB 4777735E+50 4314333E+33 .3325377E++3 418333E+03 3325177E+03 41.9933E+40 23345496+00 10+3 E + C 3 E + 13 医中华 E+C) 3010323E+0 49+5+39E+C 19434947464 3651172E+ŭ| 6939:23E+∂ 3327 + 62E+C 45+5+33E+01 251+336E+11 4414423E+0 3114258E+0 C+32219664 3175593E+0 471442" E+0 7111323E+ 31386355+7 311122E . 314933 3169335 3327452 2374549 -. 1415356+00 -. 418 4256+00 -. 18163386+00 -. 18563386+00 -2561294E+JP -2561294E+JP -276594516+00 -4385461E+50 -2655022E+00 - 2567 d 56 + 60 - 6267 -.922:836E-02 -.3625;836E-02 -.4776969E-02 -.2199936E+00 -.215,122E+00 -1217283E+00 -14877353E+00 -2719608E+00 .27196.3E+ua .1657.53E+ua -.1267288E+ua -.1761245E+40 .32112f36+40 .1.67728E+40 -- 218716 1E-61 -- 2188332E+63 - 477216E-31 .3.20154E+48 -.1021279E+50 -.26219:4E+00 -. 1662135E-01 -.41.E7729E+ c0 -. 3211253E+43 -. 1771955E-U2 -- 16E7488E+60 .1778592E+39 -. 276:9455+30 . 251 £ 9#7 E+00 . 3961294E+50 .171.1245E+60 .211.332E+60 .218716JE-U1 -. 56' 192 E+11 -. 16' 192 E+11 - 5 2 3 6 5 7 1 E - 1 1 - 5 6 5 1 E 4 5 7 1 E 4 E 5 + 7 3 - - 2 3 5 3 ( 5 9 E + 7 3 .18422376+31 -2247295E+13 -78778.6E-11 -3233729E-11 -,31,81179E+48 -,2949648E+10 E+13 -,3537'54E-01 -,28687517+90 115526610 . 3C 27 37 6E+n3 .18(f.82'E+10 E-11 -. 3 5 5 5 2 1 2 2 + 7 9 -. 522f 74 3E-11 --19544326+40 . 2 24 545 35+19 -, 3 E 2 5 75 25+17 -.+827135E+10 .32191925+05 -.21596356+10 -. 3537 5 6-11 --+1016465+93 . 5 3 9 8 5 7 1 E- 1 1 . L 5 5 5 ( 5 1 E+ 1 A -- 22291E 4E+1)1 -, 14339335+10 -, 3205925E+10 . 7 4 96 4 3 26-41 .24134255+43 . \$ 2171 k : E-31 -.365f 21 2E+90 15529356+33 -,193917 6E-11 -,2229154E+11 -, 28687F15+10 .15586315433 .31 819! 75+n; --+89323FE+33 -. + 53 323"E+1 .222.723E+11 -. 39 6 94; 3E-1; .22217235+1 -.28431591 175756++ -. 27 59F3--193511





10.76 00.00 99.00 87.07 92.00 95.0) €4. 19 .1571371E+01 .7157345E+00 .1355337E+01 .1455937E+01 .75415937E+01 .8525911E+01 .8214279E+01 .179331E+01 .5232129E+01 .51572226+G3 .9171337E+G3 .1173936E+31 .5331195E+93 .13563J7E+61 .7+71224E+09 .7856537E+00 6434298E+39 ,55747545+01 ,3477343E+01 1300 163E+11 日中・ロ E+3 93347346460 40+3 .835+153E+G1 E+0) E+i) E+1.1 92324116 59037356 7725565 5930125E .47697228 • 92673756 • 99253498 • 1257838 .7991155E . 551.843338 . 94.49383 . 94.69383 . 93.9938 . 93.9038 . 93.9038 . 93.9038 . 93.9038 . 93.9038 . 93.9038 . 93.9038 . 3743398 5365715 5235109 511 5255 1315236 3121264 153:353 6583865 11388343 1253.37 -14661349E+00 -1436974E+00 -21517916+00 -4208666+00 --4166352E+00 --13874E9E+00 -2126582E+00 -.13759938--60 -.137599636-60 -.137599636-60 -.13753936-60 -.7115156-60 -.87252326-61 \*4323985E+90 \*6476823E+00 \*-1253963E+01 \*-4167156E+60 \*22667,9E+00 - 627726EC-10 - 627775EC0 - 2386193EC0 - 29862 --7451337E+30 -1519449E+00 -4787898E+02 . 6666519E+46 -.75934J1E+80 -.5137479E+60 .7466359E+00 .7466359E+00 .1919739E+00 .9722241E-61 .5714213E+33 -.5633713E+08 -.8902671E-01 -.5.207631E+00 .1.817345E+00 -•{ 659983E+60 -. 4 3f £334E+20 •2524972E+6J -.6819647E-01 -.7.81333E+60 .7.8981 JE+00 .31471762+03 -.582F381E+U0 -.63571?7E+00 -.36445:2E+60 -.9848511E+00 .1145J97E+61 . 29! Eur 7E+63 -.1:25316E+01 -3137911E+u0 -. 6657715E-0 -712364 6 6 13 -772647 4 6 + 13 -7154165 6 + 13 -175167 9 6 + 11 - 347 642 66+30 - 337 38175+39 - 347 18 35+99 .108573.E+11 .2027821E+10 .3781652E-11 -.328227 5E+00 -31748 1E+10 -150752 (5+90 -.+545417E+11 -.2[29181E+10 .17871E9E+10 -.39:035 15+33 -.51 6995 (5+ 18 .5153954E+10 -.5434427E+10 .888791' E-12 • + 554979E+00 • 3 1 B 2 F 4 E E + 9 A -.5315159E+10 -+351234 3E+19 . 5 2tr 7 35 1 5+ 93 .5738126 [+0] 2421 15-11 -. 5 31 8 3E 4E+0.) •53:Eff: E+93 -. 318(182E+00 .37271915+73 -- 11 931 1: 5+57 .17521 95+10 .17521 95+10 .1795495E+0 £+13 . 7 15 9 34 3 F- 11 --176375?E+11 13675 85+7 ##32816£££\* -, 3 8 1 31 5 2 7 + 0 ( , 5 3 2 2 f f. 0 5 + 0 ( -,35352555 -,31215563 -,47115445 -,1244653 -. 5 19 34 2 2 .2F5192i -- 1674187 -, \$636389 .3876143 110



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212	14634	3844262E+n6	-	211.1.0	. 131	
213	12724	.3125743E+30	ï	212.0.0	. 125	
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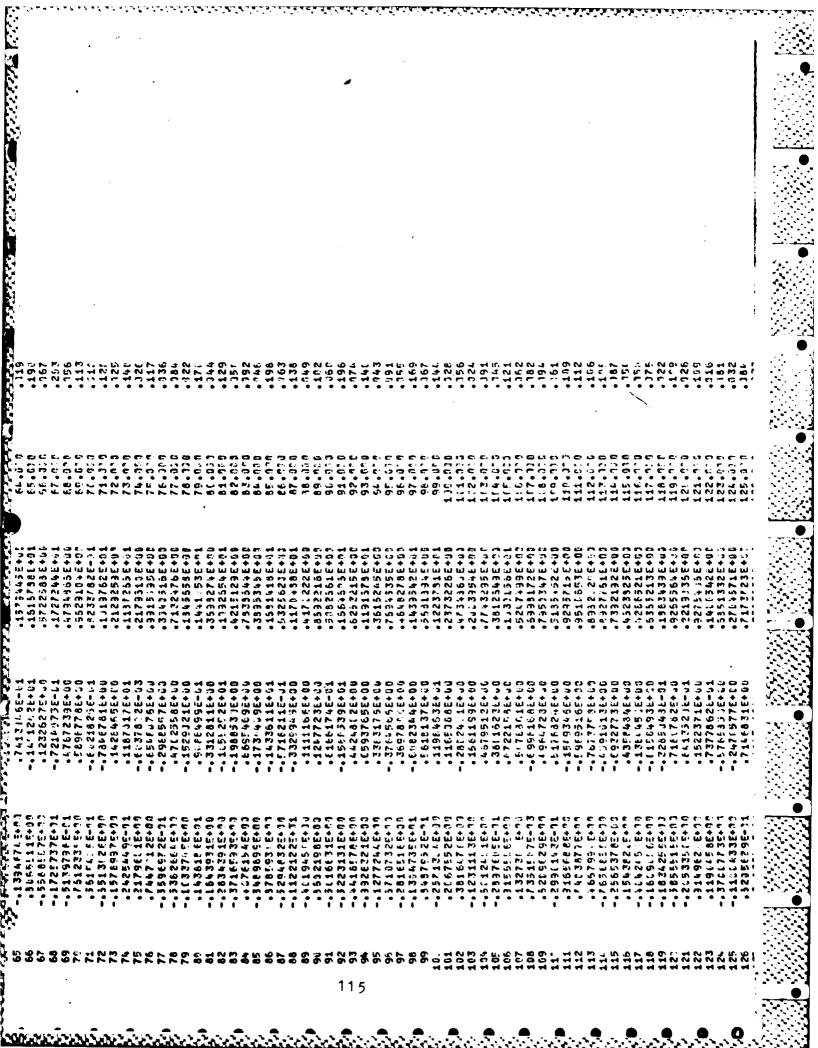
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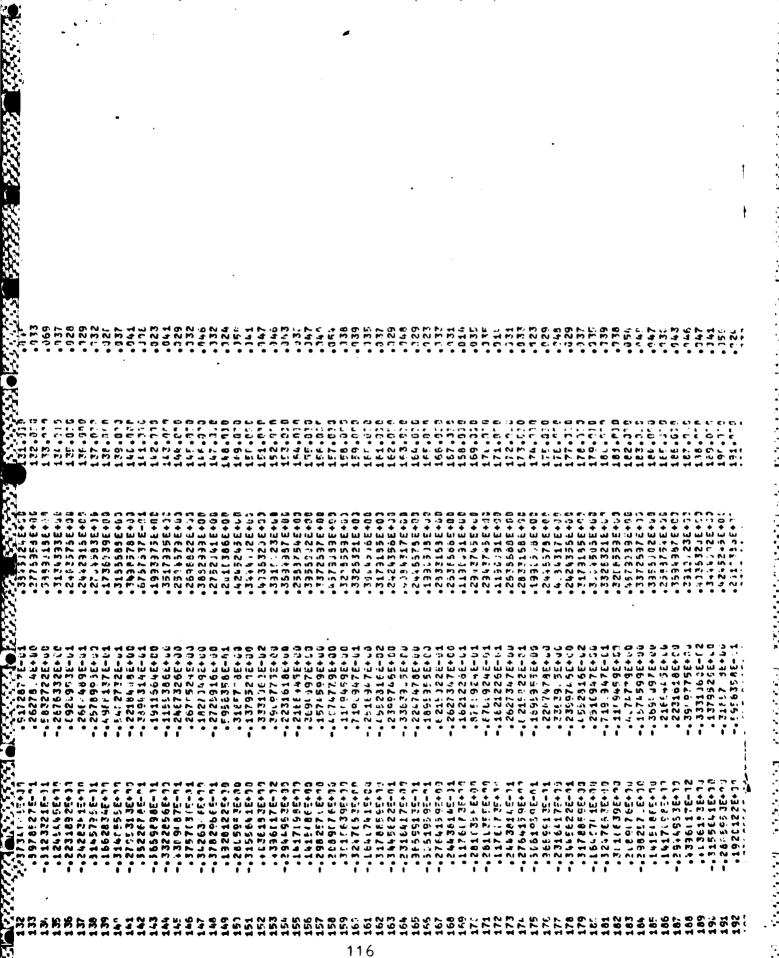
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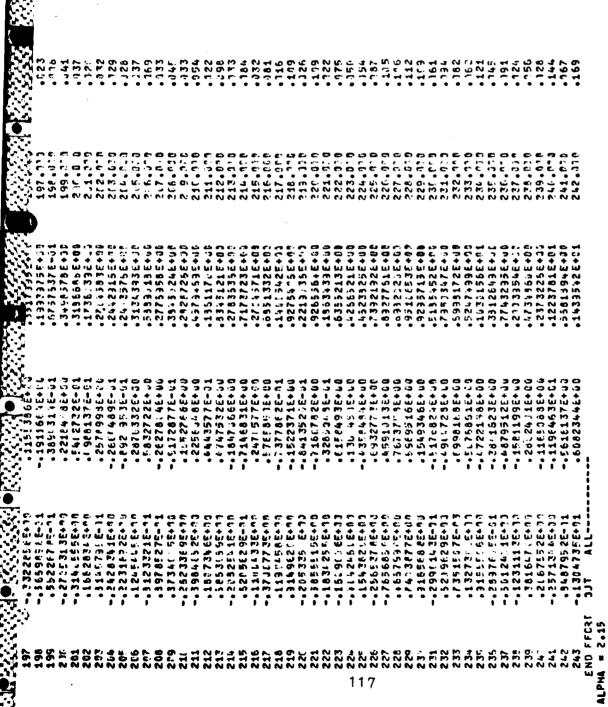
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ANY EPPEASING PROVINCE STATES OF LONGON





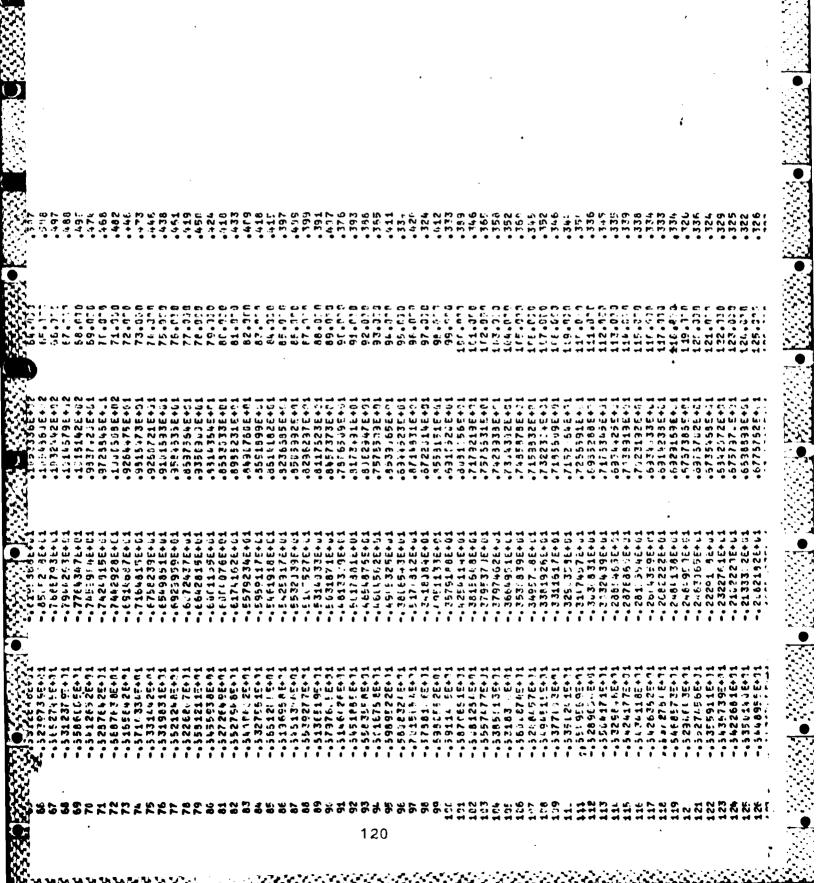


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152.189 164.196 15.916 15.742 . 226 .458 .39 0.00. .938 16.33 m 16. 15 .01 . 22.98 1:0.62 1 1 4 4 C P 16.00 23.07 25.03 0 3.00 .... 21.03 24.37 . 43.9 -2372876+:4 -33652196+03 -32599746+99 E+12 .2.81254E+u2 .13137u3E+u2 .1586925E+02 .1594953E+02 1335393E+C2 6315516E+42 .5145332E+c2 3135542E+02 2930315E+02 2421386E+92 225212dE+12 1437364E+12 1419:346+02 3333317 E+72 26453F+R 1533588E+0 .8752130E+0 3755412E+2 25731966+0 .13.2320 .12523596 .1252:236 .12379336 .1159236 .127.13266 .11341736 11322536 •51:5292E •4524238E 8175415 27.954591 +516612 1755193 1533735 1473354 12255774 4951125 4313356 3636333 3339545 240: 277 1378:32 1905391 1355319 1759564 13+4776 1317784 6261544 3:33722 2134215 1533+7 1524327 .1333.15 -. 119 75 1 3E+ u 3 5+05 -. 2:76986E+u+ -. 12, 4 JB5E+C3 -. 315 5 384E+ 63 --1336161E+03 -. 78823465+02 -. £ 94 F 533E+ L2 .. 4192597E+62 -.274.2755E+02 -. 2527356E+A2 -. 22954735+02 -. 27 32569E+02 -.1938465E+62 -.1817053E+U2 -.162: 755E+32 -.162u825E+u2 -.13F5463E+12 -. 12362.9E+P2 -. 131E 561E+ c2 -.1187353E+02 -. 12' F731E+22 -. 1188479E+t2 -.158 J37E+u2 -. 343£J11E+02 -• 347 360 7 E+ 0 2 . 2481 471E+02 -. 2287337E+62 -. 216:856E+02 -. 1741181E+#2 •.1:68323E+u2 -. 112274 3E+ u -. 8548536E+U) -. 26884+5E+L -. 21'6 339E+0 -. 1653177E+ U - 1555233E+0 . 14.3924 4E+0 -. 1132191E+C 9642921E+C -. ( 10 2131E+ .. 4796745E+0 ..4575239E+0 - 39784T 3E+6 . 3r. 26582E+ -.1543621E+U -. 1362779E+U .. 1362557E+6 -. 1121535E+6 -- 1020563E+U -. 15469536+6 -. 49f 133+E+ -- 1471957 . Sc4 £ 997 -. 1744851 2542266 -- 21 1211 2E+12 -- 21 1211 2E+12 -- 37 4 358 3E+11 .. 353721 3E+12 -. 307915 FF+93 --1217564E+32 --14282835+12 -.7285557E+91 -.7712693E+91 -.14649122+92 -.1552271E+A2 --101614517 -.1677625E+12 -. 27937685+12 -.5165131E+G -,763974 EE+11 -. 3 9 9 5 2 7 5 5 + 1 1 -.33681176+11 -. 5 FC 916 6E+ 31 -. FS48318E+)1 E+11 -. £ 958f 31E+11 -.511F32FE+31 -.3931(5 / E+0) -. 3 98556 r E+11 -.775 US 5 2E+1; -. \$ 1 4 974 1 E+ 1 -.531363£E+U -.365927E+1 -. 5445 61 25+4 -- 544 167 75+1 -, 3572436 E+7; -. f 66 L E 5 7 E + 3 -. 53215t . E+1 -. 507 Fre Azen -. 5528654E+º 36462+9 -. 3 L 31631E+A -.7844739E+\* -. 5645f 91 E+n -. 591627 UE+D -. 3 35E5 345+9 -,5583237E -,5752541E -. 7 6 3 8 2 1 2 -. 5353:31 -. 5 5 9 9 c f 3 7 -. 3822559 -. 5948223 -.5611966 -.5745517 -. 5553592 -. 3751197 

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F. 2. 1. 3.00 A. 455555 .659277F+'1 .659377E+31 .6547640E+31 .6478981E+e1 .5438133c+31 .6436465E+61 54753635491 Eta E+11 E+(-1 E+5.1 E+01 6575' 83E+u1 E+7.1 54337215+31 11+11 E+01 5439495E+01 E+11 5494473E491 65135395431 5554341 E+ 65251315+11 555434 E+1 6513343E+0 5454583E+31 6+37531E+3 544.335E+U 5459133E+0 6353311E+0 6334373E+L 6+37531E+0 6509573E+0 4 .5525191E+. 3528392E+ 647 778 E+F 5415581E+0 5+49335E+C 5331+75E+F 6471778540 5393338E+c 6964419E+? S+368589649 5954 A 4 6 E + C 6563277E+ .65433 2E+C 5525332E+ 65122545+1 5554 Jule + 7 5596899E .67:4335 .5775752E 6511546 6453118 6473969 5334373 69465483 6353111 6524813 6399398 モイキャラシ 5453,18 5331+75 66+6549 21333,2E+31,21,21,22,3E+31 -,1579755E+ L1 E+ 5.0 E+ 40 -. F. 2E 136 9E+60 -. 26971. 9E+11 E+60 26571.96+00 80573844E+0034773855E+00 .5399922E+60 .615:112E+50 7223397E+UD .6931793E+£û .62F! 458E+uû E+01 24630656+01 -. 1326 37 7E+L1 -- 1267 J. 9E+11 -. 122f 3u4 E+31 -.1112938E+ 61 -. 1016553E+61 -. 102753E+61 -. 9425 795E+26 -. f.3: 5913E+U0 -.7223397E+U0 •• t 1!: 112E+06 -, £ 359922E+UB -. 3473955E+ 10 -44.5394 JE+30 -.2517215E+FB --159:51 "E+LJ -.7818351E-01 . 303f 5 33E- u1 2517215E+00 26 1UE 3E+ BB . 28. F 31 9E+ 6. 542! 795E+ 6. 1.337536+61 .1JEE553E+C1 40 + H . 147 267 2E+01 .13794135+01 .1616791E+91 .1879J56E+01 1£99159E+11 .18.1556E+f1 17251256+11 1967 2" 7 8+61 2322761E+L1 222911.3E+J1 -. 15 9519 3E+ L -. 1472672E+1 -. 30365396-01 .7 br 8361E-u1 .1226364E+ U1 12677 95+91 16954235+01 -. 1516791E+E -413754188+0 2,F2182E+U; -. 1 931793 159:544 1112933 .1326377 -• 533[ figure + 14 -.56P 378 1E+31 E+31 -.54541P3E+01 -. 3351739E+11 -. 5451817E+11 -. 54157175+71 -.53761: 15+1 -. 5 35 1! : 2E+ 11 \_•E4(4118E+1) -. 341419 86+1 -.5483791E+1 -. 53761: 1E+P: -. 5 4 5 17 5 2E+ " -. 539311.E+A -. 5 & 3 5 7 3 9 E+ 3 -. 535£911E+1 -. 5 64 157 2F+1 -. 3414861.E+A -. 536L739E+1 -. 545418 ZE+1 -. 64482: 75+7 -. 5437! : 6E+3 -. 545 276 RE+ 1 -. 5363¢ 9 4E+1 -. 544 352 rE+1 -. 5407657E+1 -. 536 3F 9 8F+1 -.51.371.F6E+7 -. 34482. 7-+7 -. 53547295+1 -. 541419 RE+n -.5351 F39E+3 -. 336472 QE+1 -- 340 68r 92+A -. 5 64 35 2. 5+1 -. 544.805 -. 5414.8T i -. 5415717 -.54285:71 -. 19 11 teb :--. 5407657 - 5341469 -. 5 38 26 ( 131175-121

6:4 4399 197 393 191 214.63B 199.97 276.17 271.37 2.2.32 211.10 225 . 1. 1 215.37 218.0.1 32.67 1:0.31 1522 214 . 10 21.511 28.07 160.43 31.00 38.00 20.632 -U-216 15.6. 25.95 31.15 16.52 36.2 1 - Ji 21 . 7. 22.33 24.0 30.1 266.03 216.0. 217.1-116.0 39 .0 241.03 .7256531E+61 .7152364E+11 71855096+61 7322354641 E+3 7495975E+0 7375531E+C 71732136+3 7315513E+91 8457373E+01 .9723845E+51 9837420E+01 7428339849 8J91355E+9 .8.52347E+1 7575513E+i 8172+916+0 E + 0 4235595E+0 3514192E+J 959303331+0 9351333 E+# 9537554E+ 67 22: 14 E+9 .A711831E+A 9584528546 9111593E+3 9254+75E+1 5344523E+C 8533 656+ 35.15332E+C 8591899E+3 .8314354E+0 9251721E+3 3315+73E+5 7116345 6335239 3117523 6843646 8995231 1001001 8558151 9296297 .2311617E+u1 .3361925E+01 .3+957 c86+61 .352"639E+01 .3664951E+01 • 625 6 11 4 6 + 41 • 35791 68 6 + 61 • 49511 33 6 + 61 • 3618 68 4 E + 11 • 517 ( 312 E + 61 • 33 ( 54 3 E + 61 1 324 39 6+61 37974626+31 30369316+01 31474576+11 . 5 5 2 2 0 3 9 E + U 1 5579234E+61 3291 31. 9E+61 361551.BE+01 . 461 456 25+61 .4654875E+±1 46173-9E+11 5031871E+01 1: 1 527 6+ 61 542F917E+C1 5461918E++1 • 617 • 162E+ J1 • 6 il i J75E+ 61 f %(1155E+01 66£2815E+11 60724376+41 7424315E+01 49' F 325E+ 61 FU17891E+61 53157336+01 £ 359117E+11 . f 923989E+ 61 F7FR239E+61 71648136+01 7442928E+61 74559C+E+C1 2867 45355+0 **CF69851E+21** E 914687E+ L1 - 552417 18+11 - 52896548+11 - 55495596+11 -.549451 5E+11 -.549451 5E+11 -.5248+57E+11 -.516588.25+71 -.568762.85+71 -.528768.28+91 -.541285.28+91 0.1 -.551(87/E+)1 -.53183:4E+)1 -. 533(241E+11 -. 587 PE 51E+31 -• 57 97 FI 5 E+ 11 -•533141, 25+71 -- 599C! 5 2E+1 -,76151545+); -,58)8324E+21 -. 5995522E+71 -. 5136!15E+11 -.31965E PE+ 11 -- 3 L C C 4C 2E+F -. 552794 5E+1 -. 5 0 5 1 2 9 4 E+P -. 3 9114; FE+1; -. 545188F 2+0; - • 5 £ 3 9 £ 7 F + 7 . -. 52726 4 9E+A -. 3 E 2 1 2 !. RE+1 - 5 31 98 3 1E+1 -.571L334E+A -. 5395112E+) -. 5557477E+9 -. 57881. FE+" -. \$1 1£75 6E+7 -. 35335E RE+1 -. 514612FE+1 -. 54613. J.E+1 -.56512. \* 5+C -. 54359365+7 -, 5 5 8 1 21 1 E+7 -. 52268. 7E+7 FFCRF 122

Appendix F
Calculations and Tables
Showing Cost Comparisons

Calculations For 5 HP Motors

- #1 Energy Efficient (uncont) VS Standard (uncont)
- HP 8760 HR/YR X \_\_ Watts/HR X \$.06/KWH X KW/1000 = Savings/YR
- 5 8760 HR/YR X 64 W/HR X \$.06/KWH X KW/1000 W = \$33.63/YR
- 4.5 8760 HR/YR X 97 W/HR X \$.06/KWH X KW/1000 W = \$50.98/YR
- 4.0 8760 HR/YR X 129 W/HR X \$.06/KWH X KW/1000 W = \$67.80/YR
- 3.75 8760 HR/YR X 64 W/HR X \$.06/KWH X KW/1000 W = \$33.63/YR
- 3.0 8760 HR/YR X 120 W/HR X \$.06/KWH X KW/1000 W = \$63.07/YR
- 2.5 8760 HR/Yr X 118 W/HR X \$.06/KWH X KW/1000 W = \$62.02/YR
- 2.0 8760 HR/YR X 116 W/HR X \$.06/KWH X KW/1000 W = \$60.97/YR
- 1.25 8760 HR/YR X 113 W/HR X \$.06/KWH X KW/1000 W = \$59.39/YR

0.75 8760 HR/YR X 113 W/HR X \$.06/KWH X KW/1000 W = \$59.39/YR

#### 5 HP

## #2. Energy Efficient (uncont) VS Standard (cont)

HP 8760 HR/YR X \_\_\_ Watt/HR X \$.06/KWH X KW/1000W = \$\_ /YR

- 5 8760 HR/YR X <u>64</u> Watt/HR X \$.06/KWH X KW/1000W = \$33.63/YR
- 4.5 8760 HR/YR X <u>151</u> Watt/HR X \$.06/KWH X KW/1000W = \$79.36/YR
- 4.0 8760 HR/YR X 108 Watt/HR X \$.06/KWH X KW/1000W = \$56.76/YR
- 3.75 8760 HR/YR X <u>54</u> Watt/HR X \$.06/KWH X KW/1000W = \$28.38/YR
- 3.0 8760 HR/YR X 77 Watt/HR X \$.06/KWH X KW/1000W = \$40.47/YR
- 2.5 8760 HR/YR X <u>20</u> Watt/HR X \$.06/KWH X KW/1000W = \$\_10.51/YR
- 2.0 8760 HR/YR X -41 Watt/HR X \$.06/KWH X KW/1000W = \$-21.54/YR
- 1.25 8760 HR/YR X  $\frac{-79}{}$  Watt/HR X \$.06/KWH X KW/1000W = \$-41.52/YR
- 0.75 8760 HR/YR X -130 Watt/HR X \$.06/KWH X KW/1000W =  $\frac{-68.33}{YR}$

## #3. Energy Efficient (cont) VS Standard (cont)

- HP 8760 HR/YR X \_\_\_\_ Watt/HR X \$.06/KW X KW/1000 W = \$/YR
- 5 8760 HR/YR X 67 Watt/HR X \$.06/KW X KW/1000 W = \$35.22/YR
- 4.5 8760 HR/YR X <u>110</u> Watt/HR X \$.06/KW X KW/1000 W = \$57.82/YR
- 4.0 8760 HR/YR X 63 Watt/HR X \$.06/KW X KW/1000 W = \$33.11/YR
- 3.75 8760 HR/YR X 47 Watt/HR X \$.06/KW X KW/1000 W = \$24.70/YR
- 3.0 8760 HR/YR X 46 Watt/HR X \$.06/KW X KW/1000 W = \$24.18/YR

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- 2.5 8760 HR/YR X 80 Watt/HR X 0.06/KW X KW/1000 W = 0.05/YR
- 2.0 8760 HR/YR X 3 Watt/HR X \$.06/KW X KW/1000 W = \$ 1.58/YR
- 1.25 8760 HR/YR X <u>18</u> Watt/HR X \$.06/KW X KW/1000 W = \$ 9.46/YR
- 0.75 8760 HR/YR X <u>20</u> Watt/HR X \$.06/KW X KW/1000 W = \$10.51/YR

ዾኯኯኇዸፙዸኯቜዸቔኯጜጜጜጜጜፙጜዄዄዄዀዸኯፙኯዾቚፘቑፙኯቔቝዀቑዄቔዀቔቑቔቔቔቔቔቔቔጜጚጜጜጚጜጚፙጜፙጜጜጜጜጚጜጜጜጜጚጜጜጚጜዹጚጜጜጜዹ

5 HP

# #4 Energy Efficient (cont) vs Standard (uncont) 8760 Hr/Yr x \_\_\_ Watt/HR x \$.06/KWH x KW/1000W=\$/YR

НР				
5	67	W/HR	=	\$35.22/YR
4.5	56	W/HR	=	\$29.43/YR
4.0	84	W/HR	=	\$44.15/YR
3.75	57	W/HR	=	\$29.96/YR
3.0	90	W/HR	=	\$47.30/YR
2.5	178	w/HR	=	\$93.55/YR
2.0	161	W/HR	=	\$84.62/YR
1.25	209	W/HR	=\$	3109.85/YR
0.75	263	W/HR	=\$	3138.23/YR

### 5 HP

## **#5** Standard (cont) VS Standard (uncont)

HP 8760 HR/YR X \_\_\_\_ Watts/HR X \$.06/KWH X KW/1000 W = \$/YR

- 5 8760 HR/YR X 0 W/HR X \$.06/KWH X KW/1000 W = \$000.00/YR
- 4.5 8760 HR/YR X -54 W/HR X \$.06/KWH X KW/1000 W = \$-28.38/YR
- 4.0 8760 HR/YR X 21 W/HR X \$.06/KWH X KW/1000 W = \$ 11.04/YR
- 3.75 8760 HR/YR X 10 W/HR X \$.06/KWH X KW/1000 W = \$ 5.26/YR
- 3.0 8760 HR/YR X 43 W/HR X \$.06/KWH X KW/1000 W = \$22.60/YR
- 2.5 8760 HR/YR X 98 W/HR X \$.06/KWH X KW/1000 W = \$51.50/YR
- 2.0 8760 HR/YR X 158 W/HR X \$.06/KWH X KW/1000 W = \$83.05/YR
- 1.25 8760 HR/YR X 192 W/HR X \$.06/KWH X KW/1000 W = \$100.92/YR
- 0.75 8760 HR/YR X 243 W/HR X 0.06/KWH X KW/1000 W = 127.72/YR

### 5 HP

- #6 Energy Efficient (cont) VS Energy Efficient (uncont)
- HP 8760 HR/YR X \_\_\_ Watt/HR X \$.06/KWH X KWH/1000W = \$\_/YR
- 5 8760 HR/YR X <u>3 Watt/HR X \$.06/KWH X KWH/1000W =</u>
  \$ 1.58/YR
- 4.5 8760 HR/YR X -41 Watt/HR X \$.06/KWH X KWH/1000W =  $\frac{-21.55}{YR}$
- 4.0 8760 HR/YR X -45 Watt/HR X \$.06/KWH X KWH/1000W = \$-23.65/YR
- 3.75 8760 HR/YR X  $\frac{-7}{}$  Watt/HR X \$.06/KWH X KWH/1000W = \$ -3.68/YR
- 3.0 8760 HR/YR X -30 Watt/HR X \$.06/KWH X KWH/1000W = \$-15.77/YR
- 2.5 8760 HR/YR X 60 Watt/HR X \$.06/KWH X KWH/1000W = \$31.54/YR
- 2.0 8760 HR/YR X <u>45</u> Watt/HR X \$.06/KWH X KWH/1000W = \$ 23.65/YR
- 1.25 8760 HR/YR X 97 Watt/HR X \$.06/KWH X KWH/1000W = \$50.98/YR
- 0.75 8760 HR/YR X <u>150</u> Watt/HR X \$.06/KWH X KWH/1000W = \$\_78.84/YR

Tables Showing

Cost Comparisons for

5 Horse Power Motor

5 Horse Power Motor and Controller Comparisons

CONTRACTOR OF STATE O

A=New Installation, B=Retrofit

## Simple Payback in Years

Load				Situ	Situation					
Horse										
Power	14	1B	2A	3.A	<b>4</b> A	<b>4</b> B	5 <b>A</b>	<b>5</b> B	6А	<b>6</b> B
5.0	1.22	13.22	0	1.16	16.78	28.22	ou	savings-		
4.5	0.88	8.71	0	0.71	20.08	33.78	-19.37	-19.37	-25.2	-25.
4.0	09.0	6.55	0	1.24	13.39	22.51	49.81	49.81	-23.3	-23.
3.75	1.22	13.20	0	1.66	19.73	33.18	104.56	104.56	-149.5	-149.
3.0	0.65	7.04	0	1.70	12.49	21.0	24.33	24.33	-34.9	-34.
2.5	99.0	7.16	0	0.98	6.32	10.23	10.68	10.68	17.4	17.
2.0	0.67	7.28	+23.63	25.95	86.98	11.75	6.62	6.62	23.3	23.
1.25	0.69	7.48	+12.26	4.33	5.38	9.05	5.45	5.45	10.8	10.
0.75	0.69	7.48	+7.48	3.90	4.28	7.20	4.30	4.30	7.0	7.

5 HP Savings/Year Based on \$0.06 KWH

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HP Load	Load (Situation)		Comparison	son		
	#1	<b>*</b>	£	#	<del>*</del>	<b>*</b>
ស	\$33.63	\$ 33.63	\$35.22	\$ 35.22	0 \$	\$ 1.
4.5	\$50.98	\$ 79.36	\$57.82	\$ 29.43	\$-28.38	\$-21.
4.0	\$67.80	\$ 56.76	\$33.11	\$ 44.15	\$ 11.04	\$-23.
3.75	\$33.63	\$ 28.38	\$24.70	\$ 29.96	\$ 5.26	\$ -3.
3.0	\$63.07	\$ 40.47	\$24.18	\$ 47.30	\$ 22.60	\$-15.
2.5	\$62.02	\$ 10.51	\$42.05	\$ 93.55	\$ 51.50	\$ 31.
2.0	\$60.97	\$-21.54	\$ 1.58	\$ 84.62	\$ 83.05	\$ 23.
1.25	\$59.39	\$-41.52	\$ 9.46	\$109.85	\$100.92	\$ 50.
0.75	\$59.39	\$-68.33	\$10.51	\$138.23	\$127.72	\$ 78.

Table 0

5 HP

# △ Wattage for (Situation)

- . Energy Efficient (uncont) VS Standard (uncont)
- . Energy Efficient (uncont) VS Standard (Cont)
- . Energy Efficient (cont) VS Standard (cont)
- Energy Efficient (Cont) VS Standard (uncont)
- Standard (cont) VS Standard (uncont)
- 6. Energy Efficient (cont) VS Energy Efficient (uncont)

## Savings in Watts

9#	m	-41	-45	-7	-30	09	45	97	150
\$	0	-54	21	10	43	86	158	192	243
#	67	56	84	57	06	178	161	209	263
£#	67	110	63	47	46	80	m	18	20
<b>4</b>	64	151	108	54	77	20	-41	-79	-130
#1	64	97	129	64	120	118	116	113	113
HP Load	<b>1</b>	4.5	4.0	3.75	3.0	2.5	2.0	1.25	0.75

Table P

### 5 HP

### Simple Payback

### Cost/Savings per Year

Standard \$329.00, Energy Efficient 370.00
A= Cost = \$41.00, B= Cost = \$370.00 + 20% = \$444.00
Installation Cost

HP Load	A	В
5	1.22 yrs	13.20 yr
4.5	0.80 yrs	8.71 yr
4.0	0.60 yrs	6.55 yr
3.75	1.22 yrs	13.20 yr
3.0	0.65 yrs	7.04 yr
2.5	0.66 yrs	7.16 yr
2.0	0.67 yrs	7.28 yr
1.25	0.69 yrs	7.48 yr
0.75	0.69 yrs	7.48 yr

SESSOCIAL PROFESSOR NESSESSOR SESSORS CONSESSORS SESSORS CONSESSOR CONTRACTOR DESCRIPTION

B= Retrofit - Replacing Standard Motor with Energy Efficient + 20% Motor Cost Installation

A= New Installation, Cost of Energy Efficient vs Standard Motor based on continuous operation

Table Q

### Situation #2

### 5 HP

### Simple Payback

### Cost/Savings Year

Energy Efficient Motor \$370.00 + 20% Installation = \$444.00
Power Factor Controller \$550.00 Including Installation =
\$550.00

Standard Motor Cost \$329.00

Efficient motor

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A - New installation consider cost only motor/controller
B - Retrofit standard motor with controller vs Energy

HP	Load	A	•	(B not a	valid Com	parison)
5		0	yr		3.15	yr
4	.5	0	yr		1.33	yr
4	. 0	0	yr		1.86	yr
3	. 75	0	yr		3.74	yr
3	. 0	0	yr		2.62	yr
2	. 5	0	yr		10.08	yr
2	. 0	-23.63	yr		-4.92	yr
1	. 25	-12.26	yr		-2.55	yr
0	. 75	-7.44	yr		-1.55	yr

A. Cost = Energy Efficient Motor - \$370.00 + (standard motor \$329.00 + Controller \$550.00) Cost = \$509.00

B. - Energy Efficient Motor + Installation = =\$444 + Controller Cost \$550 = +\$106 less to install Energy Efficient Motor than a controll

Table R

#3

5 HP

### Simple Payback

### Cost/Saving year

Energy Efficient (cont) vs Standard (cont)

Energy Efficient Motor \$370.00

Controller \$550.00

Standard Motor \$329.00

A - New Installation - Consider Motor/Controller Cost only.

Cost = (\$370 + \$550) - (\$329 + 550) = \$41.00

Cost = Cost of Energy Efficient Motor + Controller Minus
the Cost of Standard Motor + Controller

A
1.16 yr
0.71 yr
1.24 yr

3.75

3.0	1.70	yr
2.5	0.98	yr

Table S

1.66 yr

#4

### 5 HP

### Simple Payback

### Cost/Savings Year

Energy Efficient (cont) vs Standard (uncont)

A - New Installation - Cost = (Energy Efficient Motor +

Controller) - (Standard Motor)

Cost = (\$370.00 + \$550.00) - (\$329.00) = \$591.00

B - Retrofit - Cost = Energy Efficient Motor +

Installation + Controller

STATE STATE STATE STATE STATE STATES OF THE 
Cost = (\$444.00 + \$550.00) = \$994.00

HP Load	A	В
5	16.78 yr	28.22 yr
4.5	20.08 yr	33.78 yr
4.0	13.39 yr	22.51 yr
3.75	19.73 yr	33.18 yr
3.0	12.49 yr	21.00 yr
2.5	6.32 yr	10.63 yr
2.0	6.98 yr	11.75 yr
1.25	5.38 yr	9.05 yr
0.75	4.28 yr	7.20 yr

Table T

**#**5

5 HP

### Simple Payback

### Cost/Savings Year

### Standard (cont) vs Standard (uncont)

A - New Installation - Cost = Cost of Controller
Cost = \$550.00

B - Retrofit - Same as New Installation

HP Load	A	В
5	No Savings	No Savings
4.5	-19.37 yr	-19.37 yr
4.0	49.81 yr	49.81 yr
3.75	104.56 yr	104.56 yr
3.0	24.33 yr	24.33 yr
2.5	10.68 yr	10.68 yr
2.0	6.62 yr	6.62 yr
1.25	5.45 yr	5.45 yr
0.75	4.30 yr	4.30 yr

Table U

#6

### 5 HP

### Simple Payback

### Cost/Saving Year

Energy Efficient (cont) vs Energy Efficient (uncont)

A - New Installation - Cost = Cost of Controller

Cost = \$550.00

B - Retrofit - Same as New Installation

HP Load	A	В	
5	348.10	yr 348.10 yr	2
4.5	-25.52	yr -25.52 yr	
4.0	-23.25	yr -23.25 yr	
3.75	-149.45 y	yr -149.45 yr	5
3.0	-34.87	yr -34.87 yr	5
2.5	17.44	yr 17.44 yr	5
2.0	23.26	yr 23.26 yr	5
1.25	10.79	yr 10.79 yr	5
0.75	6.98	yr 6.98 yr	•

Table V

A MARKAR CONTRACTOR OF THE STATE OF THE STAT

Tables Showing

Cost Comparisons for

10 Horse Power Motors

10 Horse Power Motor and Controller Comparisons

A= New Installation, B= Retrofit

Simple Payback in Years

Situation  Set all B 2A 3A 4A 4B 5A 5B 6A  1.15 5.75 NONE 3.27 20.66 33.72 NONE -9.45  2.14 10.60 NONE 1.10 11.50 18.77 -14.85 -14.84 67.40  3.20 15.98 NONE 2.19 11.24 18.31 50.56 50.56 21.28  4.83 24.10 -10.94 14.49 9.42 15.37 8.84 8.84 11.47			1 4 11 1
lA lB 2A 3A 4A 4B 5A 1.15 5.75 NONE 3.27 20.66 33.72 NONE 2.14 10.60 NONE 1.10 11.50 18.77 -14.85 3.20 15.98 NONE 2.19 11.24 18.31 50.56 4.83 24.10 -10.94 14.49 9.42 15.37 8.84		<b>6</b> A	-9.45 67.40 21.28 11.47
lA lB 2A 3A 4A 4B 1.15 5.75 NONE 3.27 20.66 33.72 2.14 10.60 NONE 1.10 11.50 18.77 3.20 15.98 NONE 2.19 11.24 18.31 4.83 24.10 -10.94 14.49 9.42 15.37		5B	NONE -14.84 50.56 8.84
lA lB 2A 3A 4A 1.15 5.75 NONE 3.27 20.66 2.14 10.60 NONE 1.10 11.50 3.20 15.98 NONE 2.19 11.24 4.83 24.10 -10.94 14.49 9.42		<b>5A</b>	NONE -14.85 50.56 8.84
1.15 5.75 NONE 3.27 2.14 10.60 NONE 1.10 3.20 15.98 NONE 2.19 4.83 24.10 -10.94 14.49			33.72 18.77 18.31 15.37
1.15 5.75 NONE 3.27 2.14 10.60 NONE 1.10 3.20 15.98 NONE 2.19 4.83 24.10 -10.94 14.49	tuation	44	20.66 11.50 11.24 9.42
1.15 5.75 2.14 10.60 3.20 15.98 4.83 24.10 -	Si		3.27 1.10 2.19 14.49
1.15 2.14 3.20 4.83		2A	NONE NONE NONE -10.94
		18	5.75 10.60 15.98 24.10
3			1.15 2.14 3.20 4.83
HOE HOE 10 10 2.5	Horse		10 7.5 5.0 2.5

Table W

\$-89.88

\$12.61

\$39.94

\$74.11

\$96.18

\$107.22

\$11.04

\$-63.07

\$33.11

2.5

Table X

10 HP

Wattage for (Situation)

- . Energy Efficient (uncont) VS Standard (uncont)
- 2. Energy Efficient (uncont) VS Standard (cont)
- . Energy Efficient (cont) VS Standard (cont)
- Energy Efficient (cont) VS Standard (uncont)
- . Standard (cont) VS Standard (uncont)
- Energy Efficient (cont) VS Energy Efficient (uncont)

## Savings in Watts

<b>9</b> #	-171	24	92	141
S#	0	-109	32	183
#	93	167	171	204
**	93	276	139	21
*	264	252	63	-120
T#	264	142	55.7	. 29
ДН	10	7 7	י נ	2.5

Table 1

#1

### 10 HP

### Simple Payback

### Cost/Savings Per Year

Standard \$505.00, Energy Efficient \$665.00

$$A = Cost = $160.00, B - Cost = $665.00 + 20% = $798.00$$
  
Installation Cost

HP Load	A	В
10	1.15 yr	5.75 yr
7.5	2.14 yr	10.60 yr
5.0	3.20 yr	15.98 yr
2.5	4.83 yr	24.10 yr

A - New installation, cost of Energy Efficient vs Standard Motor based on continuous operation.

B - Retrofit - Replacing Standard Motor with Energy Efficient plus 20% of motor cost for installation.

Table Z

#2

10 HP

### Simple Payback

### Cost/Savings Year

Energy Efficient motor \$66.00+20% installation=\$798.00

Power Factor Controller \$850.00 including installation

Standard motor cost \$505.00

A- New installation - consider only motor/controller cost

B- Retrofit standard motor with controller vs energy

efficient motor

A- Cost = energy efficient motor (-\$665.00+\$850.00+\$505.00) = \$690.00

B- Cost = energy efficient motor + Installation - \$798.00
+ Controller \$850.00

HP LOAD	A					
10	4.97 yr					
7.5	5.02 yr					
5.0	20.84 yr					
2.5	-10.94 yr					

Table AA

#3

10 HP

### Simple Payback

### Cost/Saving Year

### Energy Efficient (cont) vs Standard (cont)

Energy Efficient motor \$665.00

Controller

\$850.00

Standard

\$505.00

A - New Installation

$$Cost = (\$665.00 + \$850.00) - (\$505.00 + 850)$$
$$= \$160.00$$

HP Load A

10 3.27 yr

7.5 1.10 yr

5.0 2.19 yr

2.5 14.49 yr

Table BB

#4

10 HP

### Simple Payback

### Cost/Saving Year

### Energy Efficient (cont) vs Standard (uncont)

A - New Installation - Cost = (Energy Efficient Motor +
Controller) - (Standard Motor)
Cost = (\$665.00 + \$850.00) - (\$505) = \$1010.00
B - Retrofit - Cost - Energy Efficient Motor +
Installation + Controller)
Cost = (\$798.00 + \$850.00) = \$1648.00

HP Load	A	В
10	20.66 yr	33.72 yr
7.5	11.50 yr	18.77 yr
5.0	11.24 yr	18.34 yr
2.5	9.42 yr	15.37 yr

Table CC

#5

### 10 HP

### Simple Payback

### Cost/Savings Year

### Standard (cont) vs Standard (uncont)

A - New Installation - Cost = Cost of Controller

Cost = \$850.00

B - Retrofit - Same as New Installation

KALL SERVEY PERSONAL PROGRAMM ACCOUNT SERVESSES

HP Load	A	В
10	No Savings	No Savings
7.5	-14.84 yr	-14.84 yr
5.0	50.56 yr	50.56 yr
2.5	8.84 yr	8.84 yr

Table DD

#6

### 10 HP

### Simple Payback

### Cost/Saving Year

Energy Efficient (cont) vs Energy Efficient (uncont)

A - New Installation - Cost = Cost of Controller

Cost = \$850.00

B - Retrofit - Same as New Installation

HP Load	A	В
10	-9.45 yr	-9.45 yr
7.5	67.40 yr	67.40 yr
5.0	21.28 yr	21.28 yr
2.5	11.47 yr	11.47 yr

Table EE

Appendix G

Tables Showing Comparisons

of Actual Motor Data and

Simulated Data

5 Horse Power Energy Efficient
Comparison of the Manufacturer's Motor Performance
Data Versus the Computer Generated Data

HP	Amps		Watts		-		Efficiency (Percent)		Power Factor (Percent)	
	*	**	*	**	*	**	*	**	*	*
5.0	12.3	12.2	4288	4278	1751	1748	87.0	88.0	87.4	87.8
4.5	11.3	10.9	3424	3368	1761	1760	87.1	88.0	82.9	84.9
3.75	9.9	9.5	3214	3197	1763	1763	87.0	88.0	81.5	84.1
3.0	8.3	8.0	2586	2547	1771	1771	86.5	88.0	78.0	79.6
2.0	6.4	6.4	1775	1743	1781	1781	84.0	85.0	69.1	68.8
0.75	4.9	4.9	797	784	1792	1793	70.1	70.0	40.9	40.2

<sup>\*</sup> Manufacturer's Data

Table FF

<sup>\*\*</sup> Computer Data

5 Horse Power Standard

Comparison of the Manufacturer's Motor Performance

Data Versus the Computer Generated Data

HP	Amps		Wat	Watts		Speed (RPM)		Efficiency (Percent)		Power Factor (Percent)	
		**	*			**			*	**	
5.0	7.0	6.9	4423	4342	1746	1744	84.3	86.0	78.7	79.0	
4.5	6.5	6.4	3983	3882	1753	1750	84.3	86.0	76.6	76.4	
3.75	5.8	5.7	3353	3261	1763	1759	83.4	85.0	72.5	71.6	
3.0	5.2	5.2	2712	2668	1770	1768	82.5	84.1	65.7	65.1	
2.0	4.5	4.5	1870	1870	1780	1779	79.8	80.0	52.1	52.1	
0.75	3.9	3.9	874	896	1793	1792	64.0	62.0	27.7	28.4	

<sup>\*</sup> Manufacturer's Data

Table GG

<sup>\*\*</sup> Computer Generated Data

10 Horse Power Energy Efficient

Comparison of the Manufacturer's Motor Performance

Data Versus the Computer Generated Data

HP	HP AMPS		Watts		SPeed (RPM)		_		Power Factor (Percent)	
	*	**	*	**	*	**	*	**	*	**
10	24.2	23.7	8354	8211	1756	1753	89.3	90.0	86.7	86.8
7.5	19.5	18.4	<b>627</b> 5	6155	1770	1766	89.2	91.0	80.7	83.9
5.0	14.7	13.6	4246	4150	1780	1778	87.8	90.0	72.7	76.2
2.5	10.6	9.9	2222	2198	1790	1789	83.9	85.0	52.8	55.6

\* Manufacturer's Data

THE SECTION OF THE PROPERTY OF

\*\* Computer Generated Data

Table HH

10 Horse Power Standard

Comparison of the Manufacturer's Motor Performance

Data Versus the Computer Generated Data

HP	P Amps		Wat	ts	Spe (RP			-	Power (Per	Factor cent)
	*	**	*	**	*	**	*	**	*	**
10	12.6	12.4	8533	8475	1755	1753	87.4	89.0	85.2	85.7
7.5	9.9	9.7	6427	6298	1771	1766	87.0	89.0	81.3	81.1
5.0	7.7	7.5	4329	4244	1780	1778	86.2	88.0	70.4	71.0
2.5	5.8	5.8	2314	2261	1790	1789	80.6	82.0	50.4	48.8

<sup>\*</sup> Manufacturer's Data

Table II

<sup>\*\*</sup> Computer Data

### VITA

Roy D. McMaster was born on 1 July 1947 in Lampassas,
Texas. He graduated from Elgin High School in Elgin, Texas
in 1965. He then enlisted in the Air Force and served as an
electronic navigational equipment repairman until 1972. He
then attended New Mexico State University under the AFIT
education and commission program. He received his
commission and Bachelor of Science in Electical Engineering.

After commissioning he served as Base Electrical
Engineer until being directed to the School of Engineering,
Air Force Institute of Technology to study for a Masters
degree in Electrical Engineering.

Permanent Address 402 E. Brenham St.
Elgin, Texas 781

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X	Motor Control							
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Power Systems  19. ABSTRACT (Continue on reverse if necessary and identify by block number)  An economic analysis of the "NOLA" Power Factor Motor Controller is accomplished and the effects of the harmonics produced by the controller are studied. The controller is placed in series with each log of various sizes of wye-connected three-phase motors. The energy saved by the controller, the power factor correction, and the reflected harmonics under varying load conditions are studied to determine the economic advantages. Also the data from the controlled motor is compared to an energy efficient motor.  An analog-digital computer program is developed which models an induction motor and the "NOLA" controller. The computer model is used to determine the economic and the "NOLA" controller.								
"NOLA" controller. The computer model is used to determine and analyze the reflected wave shape produced by the controller.								
The results of the study indicates that the energy efficient motor is the most cost effective alternative at the present time because of the high initial cost of the								
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